

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees
Search Spaces
Optimization
Problems

AOBF
Example

Weighted Heuristic Anytime Search

Flerova, Marinescu, and Dechter

Daniel Padé¹

¹University of South Carolina

April 24, 2017

Basic Heuristic Searches

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs

Pseudotrees

Search Spaces

Optimization
Problems

AOBF

Example

- **Best-first Search**
Blindly follows the heuristic
- **Weighted A^* Search**
For $w > 1$

$$f(n) = g(n) + w \cdot h(n)$$

Larger w yields 'greedier' searches

Basic Heuristic Searches

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs

Pseudotrees

Search Spaces

Optimization
Problems

AOBF

Example

- Best-first Search
Blindly follows the heuristic
- Weighted A^* Search
For $w > 1$

$$f(n) = g(n) + w \cdot h(n)$$

Larger w yields 'greedier' searches

Graphical Models

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees
Search Spaces

Optimization
Problems

AOBF

Example

Definition (Graphical Model)

A tuple $\mathcal{M} = \langle X, D, F, \otimes \rangle$ where

- 1 $X = \{X_0, \dots, X_{n-1}\}$ is a set of *variables*
- 2 $D = \{D_0, \dots, D_{n-1}\}$ is a set of *domains*
- 3 $F = \{f_0(X_{S_0}), \dots, f_{r-1}(X_{S_{r-1}})\}$ is a set of *scopes*:
 - $X_{S_i} \subseteq X$
 - $\forall i. f_i : X_{S_i} \rightarrow \mathbb{R}^+$
- 4 A *combination operator* $\otimes \in \{\Sigma, \Pi\}$

The model \mathcal{M} represents the function

$$C(X) = \bigotimes_{i=0}^{r-1} f_i(X_{S_i})$$

Graphical Models

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs

Pseudotrees

Search Spaces

Optimization
Problems

AOBF

Example

Definition (Graphical Model)

A tuple $\mathcal{M} = \langle X, D, F, \otimes \rangle$ where

- 1 $X = \{X_0, \dots, X_{n-1}\}$ is a set of *variables*
- 2 $D = \{D_0, \dots, D_{n-1}\}$ is a set of *domains*
- 3 $F = \{f_0(X_{S_0}), \dots, f_{r-1}(X_{S_{r-1}})\}$ is a set of *scopes*:
 - $X_{S_i} \subseteq X$
 - $\forall i. f_i : X_{S_i} \rightarrow \mathbb{R}^+$
- 4 A *combination operator* $\otimes \in \{\Sigma, \Pi\}$

The model \mathcal{M} represents the function

$$C(X) = \bigotimes_{i=0}^{r-1} f_i(X_{S_i})$$

Graphical Models

Optimization Problems

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees
Search Spaces
Optimization
Problems

AOBF

Example

Given a model $\mathcal{M} = \langle X, D, F, \otimes \rangle$, the most common optimization task is either *most probable explanation* or *maximum a posteriori*

MPE Find the optimal value C^* :

$$C^* = C(x^*) = \max_X \bigotimes_{i=0}^{r-1} f_i(X_{S_i})$$

MAP Find the optimizing configuration x^* :

$$x^* = \operatorname{argmax}_X \bigotimes_{i=0}^{r-1} f_i(X_{S_i})$$

Graphical Models

Optimization Problems

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees
Search Spaces
Optimization
Problems

AOBF

Example

Given a model $\mathcal{M} = \langle X, D, F, \otimes \rangle$, the most common optimization task is either *most probable explanation* or *maximum a posteriori*

MPE Find the optimal value C^* :

$$C^* = C(\mathbf{x}^*) = \max_X \bigotimes_{i=0}^{r-1} f_i(X_{S_i})$$

MAP Find the optimizing configuration x^* :

$$x^* = \operatorname{argmax}_X \bigotimes_{i=0}^{r-1} f_i(X_{S_i})$$

Graphical Models

Optimization Problems

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees
Search Spaces
Optimization
Problems

AOBF

Example

Given a model $\mathcal{M} = \langle X, D, F, \otimes \rangle$, the most common optimization task is either *most probable explanation* or *maximum a posteriori*

MPE Find the optimal value C^* :

$$C^* = C(x^*) = \max_X \bigotimes_{i=0}^{r-1} f_i(X_{S_i})$$

MAP Find the optimizing configuration x^* :

$$x^* = \operatorname{argmax}_X \bigotimes_{i=0}^{r-1} f_i(X_{S_i})$$

Graphical Models

Optimization Problems: MPE/MAP \rightarrow WCSP

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees
Search Spaces
Optimization
Problems

AOBF

Example

MPE

$$C_{\text{MPE}}^* = C(\mathbf{x}^*) = \max_{\mathbf{X}} \bigotimes_{i=0}^{r-1} f_i(X_{S_i})$$

WCSP Weighted Constraint Satisfaction Problem
(MPE in negative log-space)

$$C_{\text{WCSP}}^* := C(\mathbf{x}^*) = \min_{\mathbf{X}} \bigotimes_{i=0}^{r-1} f_i(X_{S_i})$$

Graphical Models

Optimization Problems: MPE/MAP \rightarrow WCSP

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees
Search Spaces
Optimization
Problems

AOBF

Example

MPE

$$C_{\text{MPE}}^* = C(\mathbf{x}^*) = \max_{\mathbf{X}} \bigotimes_{i=0}^{r-1} f_i(\mathbf{X}_{S_i})$$

WCSP Weighted Constraint Satisfaction Problem
(MPE in negative log-space)

$$C_{\text{WCSP}}^* := C(\mathbf{x}^*) = \min_{\mathbf{X}} \bigotimes_{i=0}^{r-1} f_i(\mathbf{X}_{S_i})$$

AND/OR Search Graphs

Primal Graph

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs

Pseudotrees

Search Spaces

Optimization
Problems

AOBF

Example

Definition

The *primal graph* of a model is a graph where the vertices are the variables and edges connect variables within the same scope

Scopes

$$\blacksquare X_{S_0} = \{A, B\}$$

$$\blacksquare X_{S_1} = \{A, C\}$$

$$\blacksquare X_{S_2} = \{C, D\}$$

$$\blacksquare X_{S_3} = \{B, D\}$$

$$\blacksquare X_{S_4} = \{B, F\}$$

$$\blacksquare X_{S_5} = \{E, F\}$$

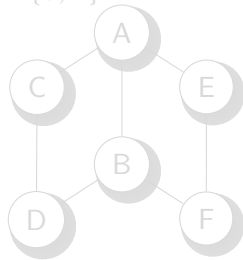


Figure: Primal

AND/OR Search Graphs

Primal Graph

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs

Pseudotrees

Search Spaces

Optimization
Problems

AOBF

Example

Definition

The *primal graph* of a model is a graph where the vertices are the variables and edges connect variables within the same scope

Scopes

■ $X_{S_0} = \{A, B\}$

■ $X_{S_1} = \{A, C\}$

■ $X_{S_2} = \{C, D\}$

■ $X_{S_3} = \{B, D\}$

■ $X_{S_4} = \{B, F\}$

■ $X_{S_5} = \{E, F\}$

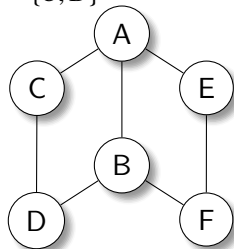


Figure: Primal

AND/OR Search Graphs

Pseudotrees

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs

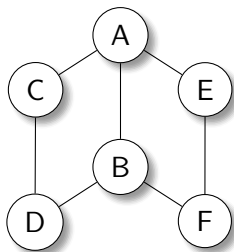
Pseudotrees

Search Spaces

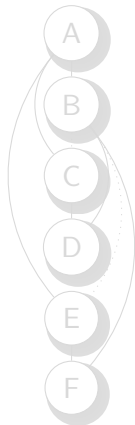
Optimization
Problems

AOBF

Example



(a) Primal



(b) Induced Graph

Figure: Induced graph over the natural ordering.

AND/OR Search Graphs

Pseudotrees

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs

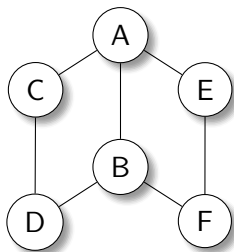
Pseudotrees

Search Spaces

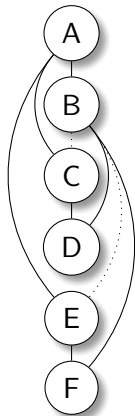
Optimization
Problems

AOBF

Example



(a) Primal



(b) Induced Graph

Figure: Induced graph over the natural ordering.

AND/OR Search Graphs

Pseudotrees

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs

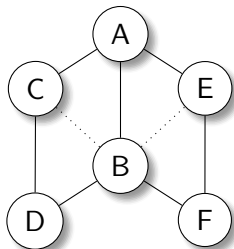
Pseudotrees

Search Spaces

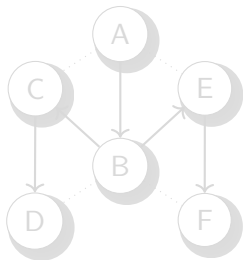
Optimization
Problems

AOBF

Example



(a) Orig + Ind. Edges



(b) Pseudo-tree

Figure: Pseudo-tree with edges chosen to respect the order

AND/OR Search Graphs

Pseudotrees

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs

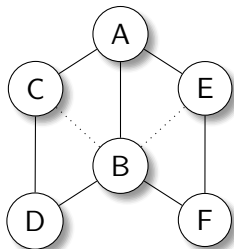
Pseudotrees

Search Spaces

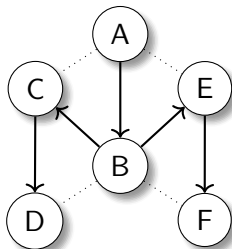
Optimization
Problems

AOBF

Example



(a) Orig + Ind. Edges



(b) Pseudo-tree

Figure: Pseudo-tree with edges chosen to respect the order

AND/OR Search Graphs

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees
Search Spaces

Optimization
Problems

AOBF

Example

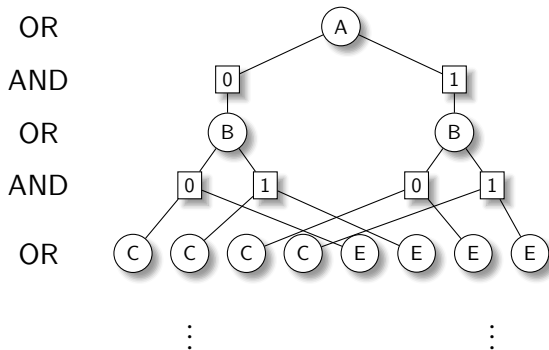


Figure: Context-Minimal AND/OR Graph For Pseudotree

AND/OR Search Graphs

Optimization Problems

WHAS

Daniel Padé

Background

Searches

Graphical
Models

Optimization
Problems

AND/OR

Search Graphs

Primal Graphs

Pseudotrees

Search Spaces

Optimization
Problems

AOBF

Example

Assume a graphical model $\mathcal{M} = \langle X, D, F, \otimes \rangle$ with primal graph G , pseudotree \mathcal{T} , and AND/OR search tree $\mathcal{S}_{\mathcal{T}}$

Definition

The *context-minimal AND/OR search graph*, denoted $\mathcal{C}_{\mathcal{T}}$, is the AND/OR search graph obtained after merging all identical subproblems.

$\mathcal{C}_{\mathcal{T}}$ is exponential in the depth of \mathcal{T}

AND/OR Search Graphs

Optimization Problems

WHAS

Daniel Padé

Background

Searches

Graphical
Models

Optimization
Problems

AND/OR

Search Graphs

Primal Graphs

Pseudotrees

Search Spaces

Optimization
Problems

AOBF

Example

Assume a graphical model $\mathcal{M} = \langle X, D, F, \otimes \rangle$ with primal graph G , pseudotree \mathcal{T} , and AND/OR search tree $\mathcal{S}_{\mathcal{T}}$

Definition

The *context-minimal AND/OR search graph*, denoted $\mathcal{C}_{\mathcal{T}}$, is the AND/OR search graph obtained after merging all identical subproblems.

$\mathcal{C}_{\mathcal{T}}$ is exponential in the depth of \mathcal{T}

AND/OR Search Graphs

Optimization Problems

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees

Search Spaces
Optimization
Problems

AOBF

Example

Assume a graphical model $\mathcal{M} = \langle X, D, F, \otimes \rangle$ with primal graph G , pseudotree \mathcal{T} , and AND/OR search tree $\mathcal{S}_{\mathcal{T}}$

Definition

A *solution tree* T of $\mathcal{C}_{\mathcal{T}}$ is a subtree satisfying the following conditions:

- 1 It contains the root of $\mathcal{C}_{\mathcal{T}}$
- 2 If an internal AND node n is in T , then all the children of n are in T
- 3 if an internal OR node n is in T , then exactly one child of n is in T
- 4 Every leaf in T is a terminal node

AND/OR Search Graphs

Optimization Problems

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs

Pseudotrees

Search Spaces

Optimization
Problems

AOBF

Example

Assume a graphical model $\mathcal{M} = \langle X, D, F, \otimes \rangle$ with primal graph G , pseudotree \mathcal{T} , and AND/OR search tree $\mathcal{S}_{\mathcal{T}}$

Definition

A *solution tree* T of $\mathcal{C}_{\mathcal{T}}$ is a subtree satisfying the following conditions:

- 1 It contains the root of $\mathcal{C}_{\mathcal{T}}$
- 2 If an internal AND node n is in T , then all the children of n are in T
- 3 if an internal OR node n is in T , then exactly one child of n is in T
- 4 Every leaf in T is a terminal node

AND/OR Search Graphs

Optimization Problems

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees
Search Spaces
Optimization
Problems

AOBF

Example

Assume a graphical model $\mathcal{M} = \langle X, D, F, \otimes \rangle$ with primal graph G , pseudotree \mathcal{T} , and AND/OR search tree $\mathcal{S}_{\mathcal{T}}$

Definition

A *solution tree* T of $\mathcal{C}_{\mathcal{T}}$ is a subtree satisfying the following conditions:

- 1 It contains the root of $\mathcal{C}_{\mathcal{T}}$
- 2 If an internal AND node n is in T , then all the children of n are in T
- 3 if an internal OR node n is in T , then exactly one child of n is in T
- 4 Every leaf in T is a terminal node

AND/OR Search Graphs

Optimization Problems

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs

Pseudotrees

Search Spaces

Optimization
Problems

AOBF

Example

Assume a graphical model $\mathcal{M} = \langle X, D, F, \otimes \rangle$ with primal graph G , pseudotree \mathcal{T} , and AND/OR search tree $\mathcal{S}_{\mathcal{T}}$

Definition

A *solution tree* T of $\mathcal{C}_{\mathcal{T}}$ is a subtree satisfying the following conditions:

- 1 It contains the root of $\mathcal{C}_{\mathcal{T}}$
- 2 If an internal AND node n is in T , then all the children of n are in T
- 3 if an internal OR node n is in T , then exactly one child of n is in T
- 4 Every leaf in T is a terminal node

AND/OR Best First Search

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees
Search Spaces
Optimization
Problems

AOBF

Example

State-of-the-art A^* for AND/OR search space.

Too complicated to fit on a slide

Highlights

- Input:
- Graphical Model $\mathcal{M} = \langle X, D, F, \Sigma \rangle$
 - Initial weight w_0
 - Pseudotree \mathcal{T} rooted at X_1
 - heuristic h_i (precalculated)

Output: Optimal solution to \mathcal{M}

AND/OR Best First Search

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees
Search Spaces
Optimization
Problems

AOBF

Example

State-of-the-art A^* for AND/OR search space.
Too complicated to fit on a slide

Highlights

- Input:
- Graphical Model $\mathcal{M} = \langle X, D, F, \Sigma \rangle$
 - Initial weight w_0
 - Pseudotree \mathcal{T} rooted at X_1
 - heuristic h_i (precalculated)

Output: Optimal solution to \mathcal{M}

AND/OR Best First Search

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees
Search Spaces
Optimization
Problems

AOBF

Example

State-of-the-art A^* for AND/OR search space.
Too complicated to fit on a slide

Highlights

- Input:**
- Graphical Model $\mathcal{M} = \langle X, D, F, \Sigma \rangle$
 - Initial weight w_0
 - Pseudotree \mathcal{T} rooted at X_1
 - heuristic h_i (precalculated)

Output: Optimal solution to \mathcal{M}

AND/OR Best First Search

Example

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR

Search Graphs

Primal Graphs

Pseudotrees

Search Spaces

Optimization
Problems

AOBF

Example

Let $\mathcal{M} = \{X, D, F, \Sigma\}$ where

- $X = \{A, B, C, D\}$
- $D = \bigcup_{s \in X} \{0, 1\}_s$
- F is given by the following tables:

A	B	$f(A, B)$
0	0	4
0	1	1
1	0	3
1	1	1

B	C	$f(B, C)$
0	0	3
0	1	2
1	0	2
1	1	1

B	$f(B)$
0	1
1	9

A	B	$f(A, B)$
0	0	4
0	1	1
1	0	3
1	1	1

AND/OR Best First Search

Example

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees
Search Spaces
Optimization
Problems

AOBF
Example

Scopes

$$F = \{f(A, B), f(B, C), f(A, D), f(B)\}$$

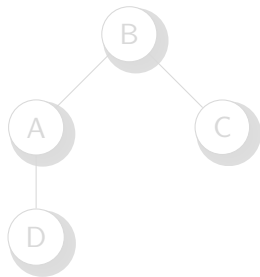


Figure: Primal Graph

AND/OR Best First Search

Example

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees
Search Spaces
Optimization
Problems

AOBF
Example

Scopes

$$F = \{f(A, B), f(B, C), f(A, D), f(B)\}$$

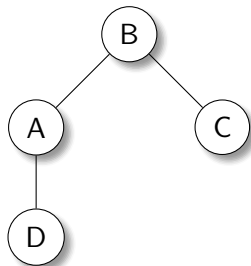


Figure: Primal Graph

AND/OR Best First Search

Example

WHAS

Daniel Padé

Background
Searches

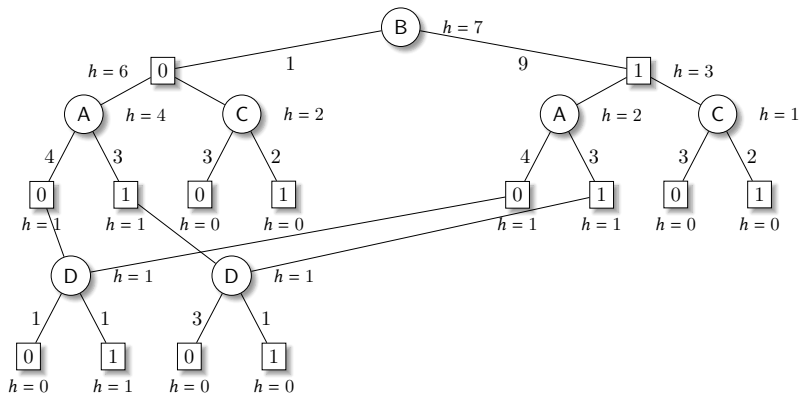
Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees
Search Spaces
Optimization
Problems

AOBF
Example



AND/OR Best First Search

Example

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees
Search Spaces
Optimization
Problems

AOBF
Example

Algorithm Sketch

Down Pass: Expand nodes and mark terminal nodes solved

Up Pass: Update $v(n)$ for each node according to the following rules:

$$\text{OR Nodes: } v(n) = \min_{k \in \text{succ}(n)} w(n, k) + v(k)$$

$$\text{AND Nodes: } v(n) = \sum_{k \in \text{succ}(n)} v(k)$$

AND/OR Best First Search

Example

WHAS

Daniel Padé

Background
Searches

Graphical
Models

Optimization
Problems

AND/OR
Search Graphs

Primal Graphs
Pseudotrees
Search Spaces
Optimization
Problems

AOBF
Example

