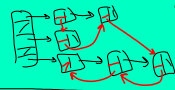


1. Augmenting data structures
 2. Dynamic Programming (start)


1. Augment an off-the-shelf data struct to support add// basic ops.
 Ex: Threaded hash table
 Hash table - linked list hybrid



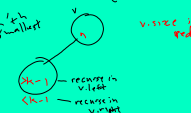
Ex: Dynamic Order Statistics
 of comparable items
 Collection that supports:
 Insert
 Delete
 Search
 Iterate in order
 Select the kth smallest element

BST

Since a BST handles most of these, that suggests we can start with a BST and augment it to handle selection.
 With standard BST, Select(k) takes time $\Theta(k)$
 [actually $\Theta(\min(k, n-k))$, where $n = \text{BST size}$]
 $k \leq \frac{n}{2}$: Iterate k items in increasing order
 $k > \frac{n}{2}$: Iterate $n-k$ items in decreasing order.



Answer:
 Include with each node v the size of the subtree rooted at v (in v 's size).



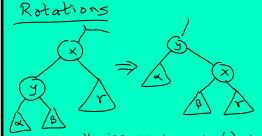
Pre-condition
 BSTSelect(root, k) // $k > 0$
 // returns kth smallest element
 // in tree rooted at root
 if root == nil then error
 else
 left.size = root.left.size
 root.left.size = 0
 if left.size = k-1 then return root
 else if left.size $\geq k$ then return BSTSelect(root.left, k)
 else // left.size < k-1 return BSTSelect(root.right, k-left.size-1)

worst-case
 Time = $\Theta(d)$ ($d = \text{tree depth}$)

Insertion(x):
 - usual BST insert at x
 - if successful, increment size of all nodes on path from root to x
 (x.size += 1)

Deletion - skip

Rotations



$X.size = X.size - size(A) - 1$
 $Y.size = Y.size + size(Z) + 1$

Check: old X.size = new Y.size
 Search & Iteration don't change.

Dynamic Programming
 Recursion can be inefficient

```

int fib(int n)
// return the n'th Fibonacci number
//
if (n==0 || n==1)
return n;
else // n>1
return fib(n-1) + fib(n-2);
    
```

$$\begin{array}{c}
 \text{fib}(4) \\
 \swarrow \quad \searrow \\
 \text{fib}(3) \quad \text{fib}(2) \\
 \swarrow \quad \searrow \quad \swarrow \quad \searrow \\
 \text{fib}(2) \quad \text{fib}(1) \quad \text{fib}(1) \quad \text{fib}(0) \\
 \swarrow \quad \searrow \quad \swarrow \quad \searrow \\
 \text{fib}(1) \quad \text{fib}(0) \quad \text{fib}(0) \quad \text{fib}(0) \\
 \swarrow \quad \searrow \\
 \text{fib}(0) \quad \text{fib}(0)
 \end{array}$$

Takes time exponential in n .

One fix: memoization

- Maintain a dictionary of (input, output) pairs of recursive calls.
- When making a recursive call, first check the dict to see if it is there. If so return output (no rec. call) otherwise
 - make the recursive call
 - when value is found add that to the dictionary.

Other method:

bottom-up table

useful when space of all subcalls can be neatly indexed in an array. Fill the array from the bottom up, computing each array entry based on previously fill entries.

Ex: Fib sequence

```

fib(n)
allocate array F[0..n]
F[0] := 0
F[1] := 1
for j := 2 to n
    F[j] := F[j-1] + F[j-2]
return F[n]
    
```

Problem: Given a list $A[1..n]$ of positive numbers. Want to find the largest sum of nonadjacent entries from A .

$\text{BigSum}(A, k)$ finds largest sum of nonadj numbers in $A[1..k]$

```

if k = 0 then return 0
if k = 1 then return A[1]
// k ≥ 2
sum1 := BigSum(A, k-1)
sum2 := BigSum(A, k-2)
return max(sum1, sum2 + A[k])
    
```

Initial call: $\text{BigSum}(A, n)$.

Dynamic Programming:

```

allocate table S[0..n]
// S[j] := BigSum(A, j)
S[0] := 0
S[1] := 1
for j := 2 to n do
    S[j] := max(S[j-1], S[j-2] + A[j])
return S[n].
    
```