

# Experimental Validation of UAV-Deployed Edge Sensors for Frequency-Based Bridge Damage Detection

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Methodology

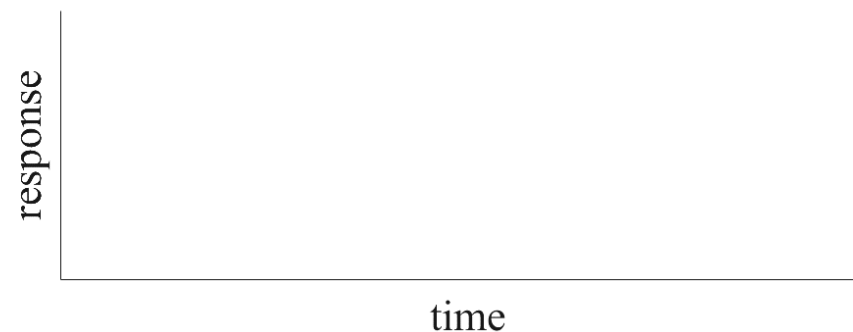
Experimentation

Results and Discussion

Future work

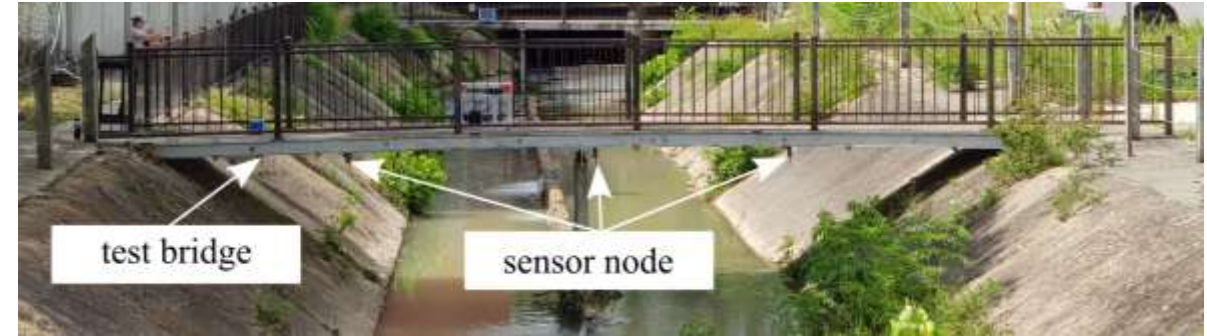
## Outline

- Introduction:
  - Rapid structural health monitoring
  - Remote SHM sensing systems
  - Limitations in bandwidth and power
- Methodology:
  - UAV-deployable sensing system
  - Wireless sensing networks
  - SHM edge-processing algorithm
- Experimentation:
  - Modal frequency detection using UAV-deployable edge-computing sensing node
- Results and Discussion:
  - Frequency responses analysis
  - Sensing system strengths and experimental challenges
- Future work:
  - Sensor network algorithm enhancements
  - Rapid modal reconstruction on-edge



## Introduction

- Rapid structural health monitoring
  - The process from data collection to state inference.
  - Involves tools to facilitate rapid inspection
  - Aids in structural assessment of structures following severe weather and environmental disasters.



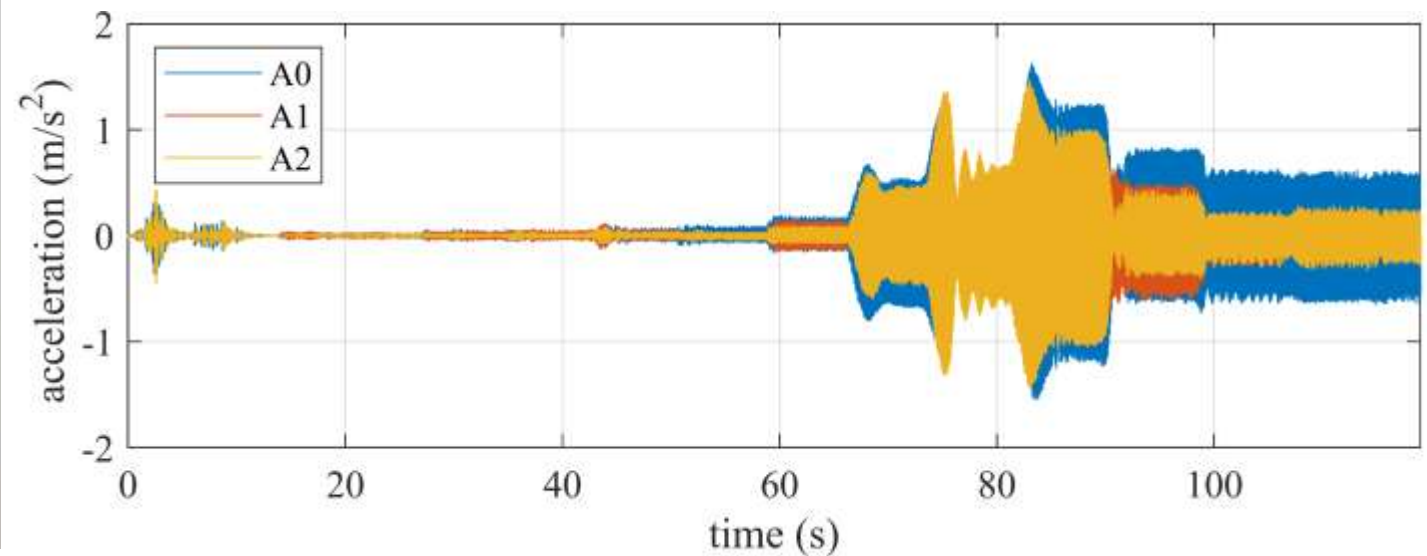
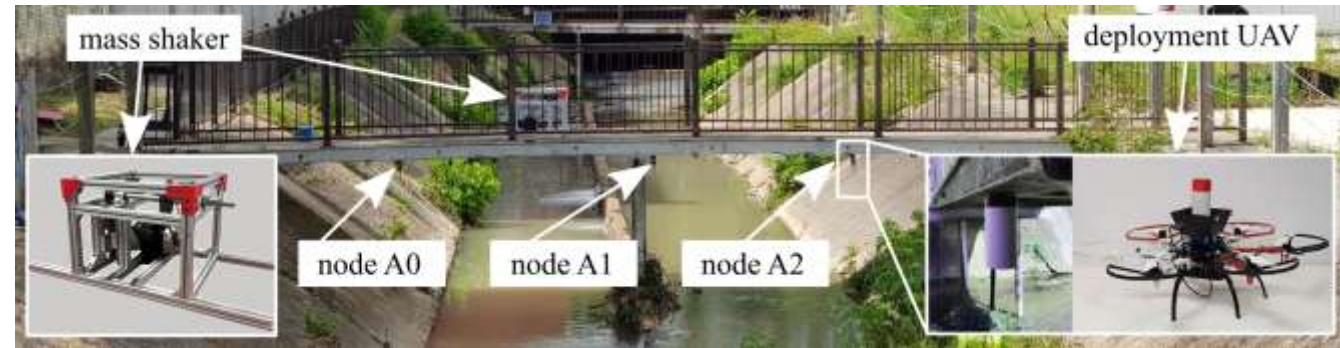
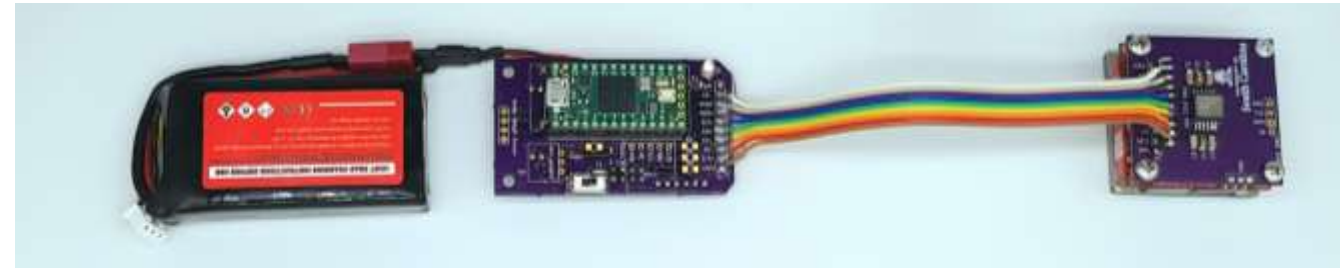
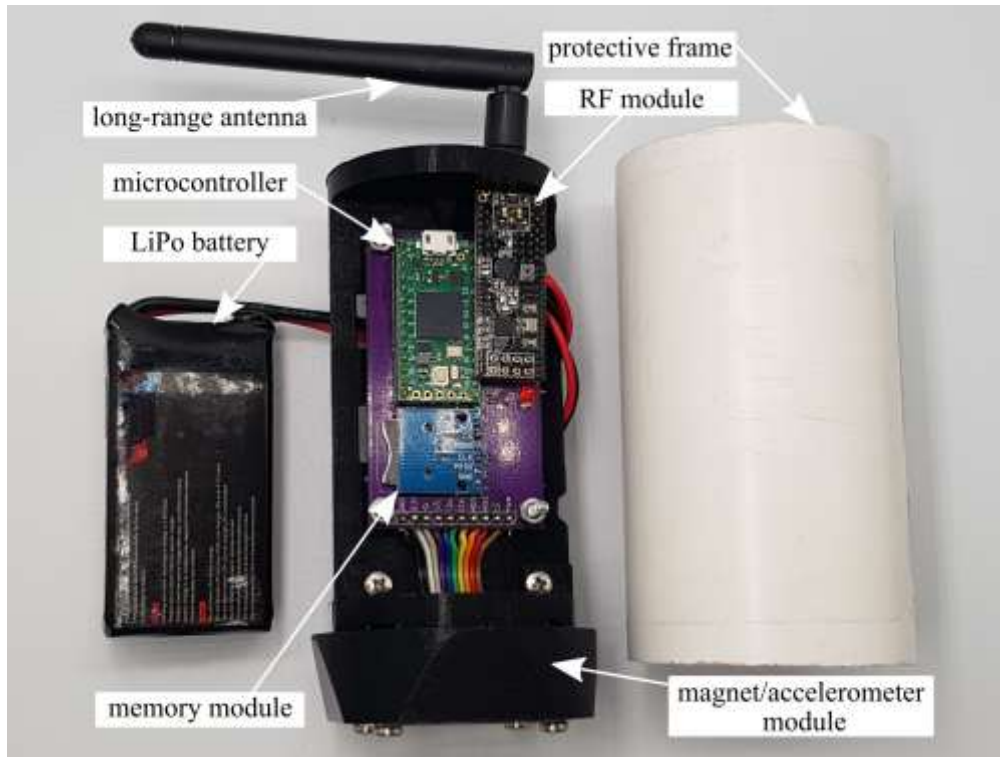
response

time



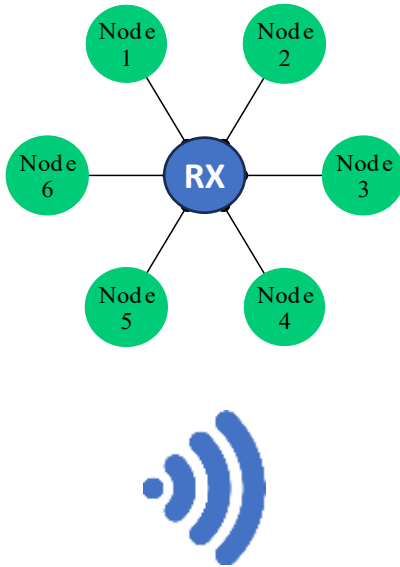
## Introduction

- Remote SHM sensing systems
  - Standalone sensing units
  - Independent power
  - Wireless transmission
  - Memory storage capability

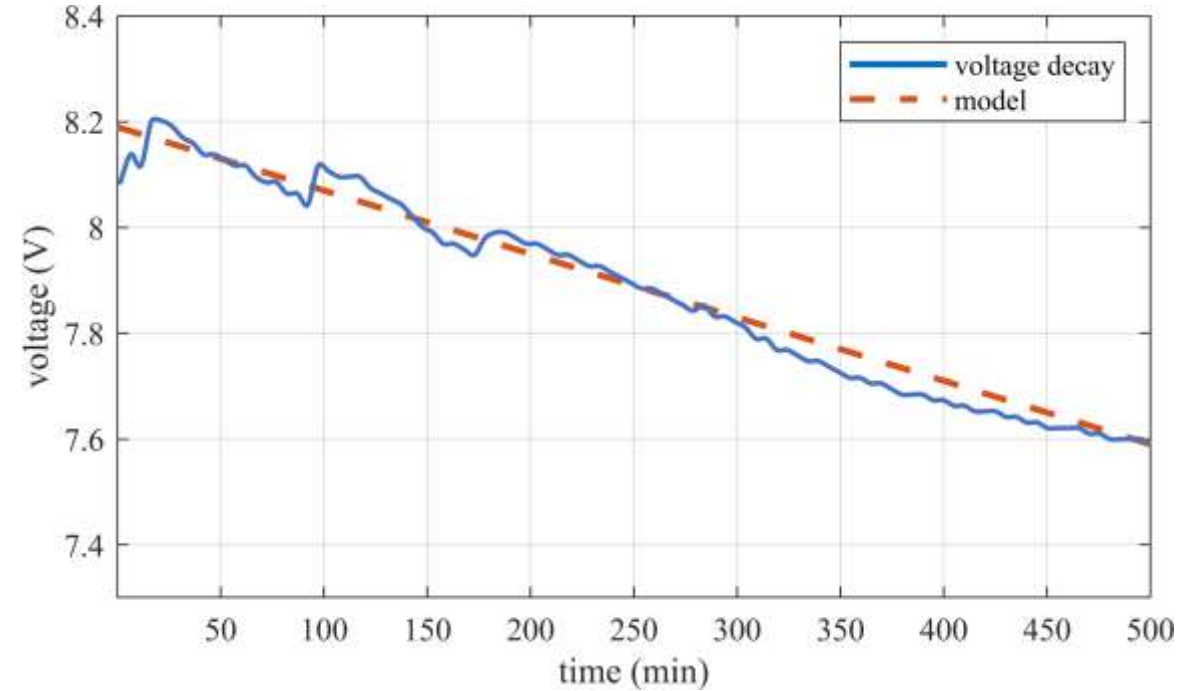


# Introduction

- Transmission bandwidth and power limitations
  - Large amounts of transmitted data
  - Cause bottle necks and power shortages



response

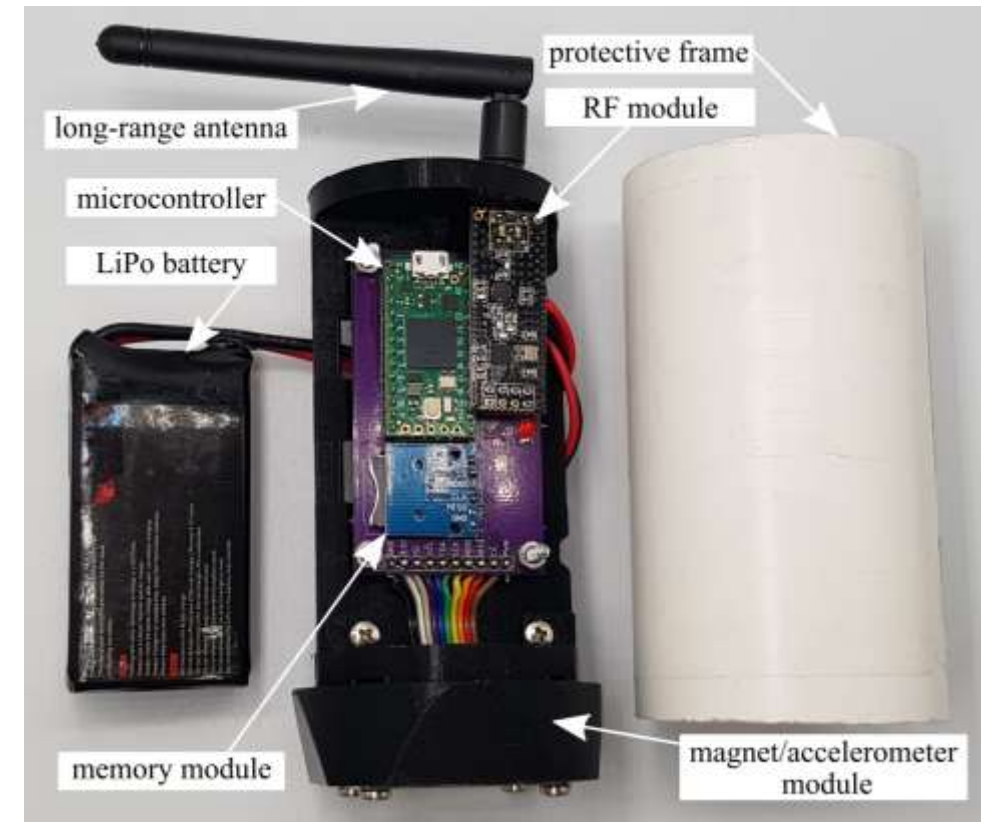
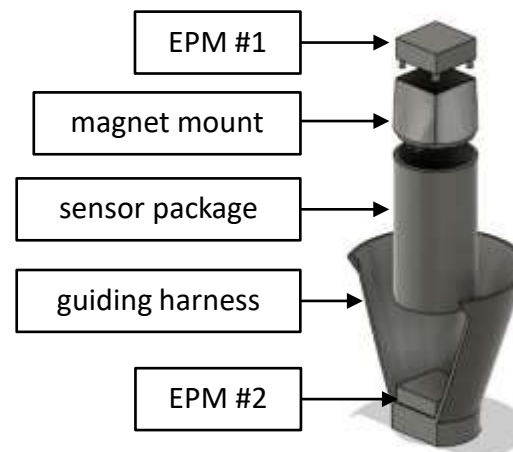
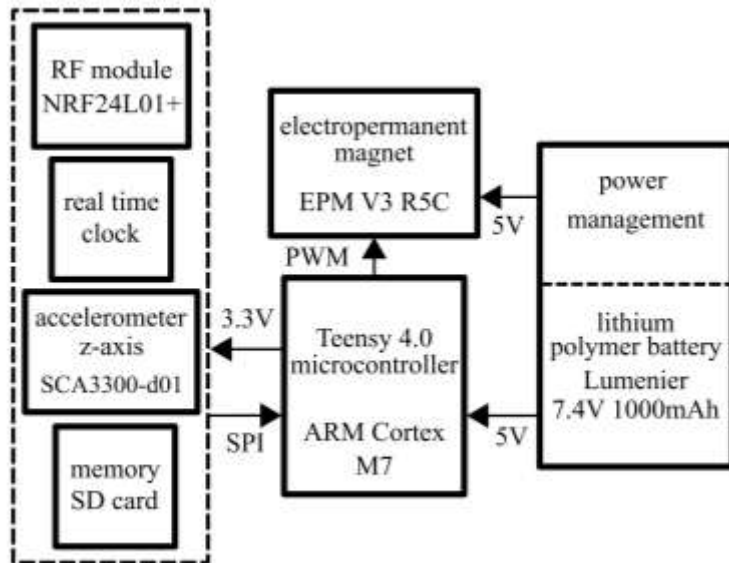
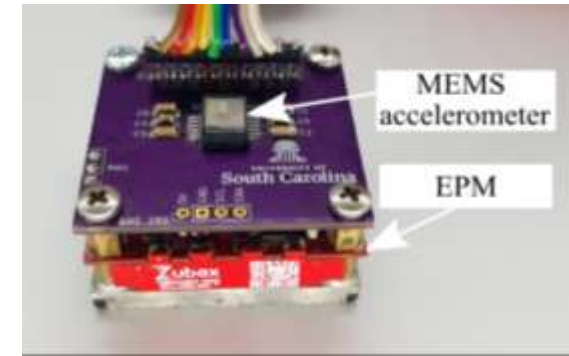
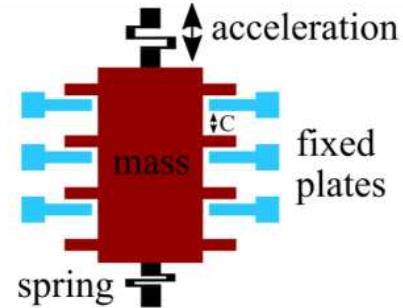


time

## UAV-deployable sensing system

### Features:

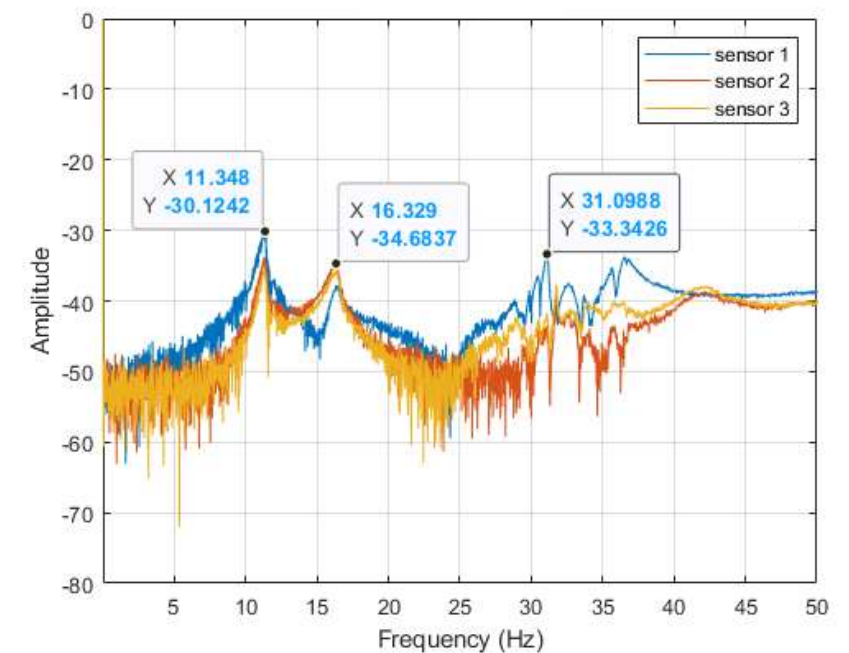
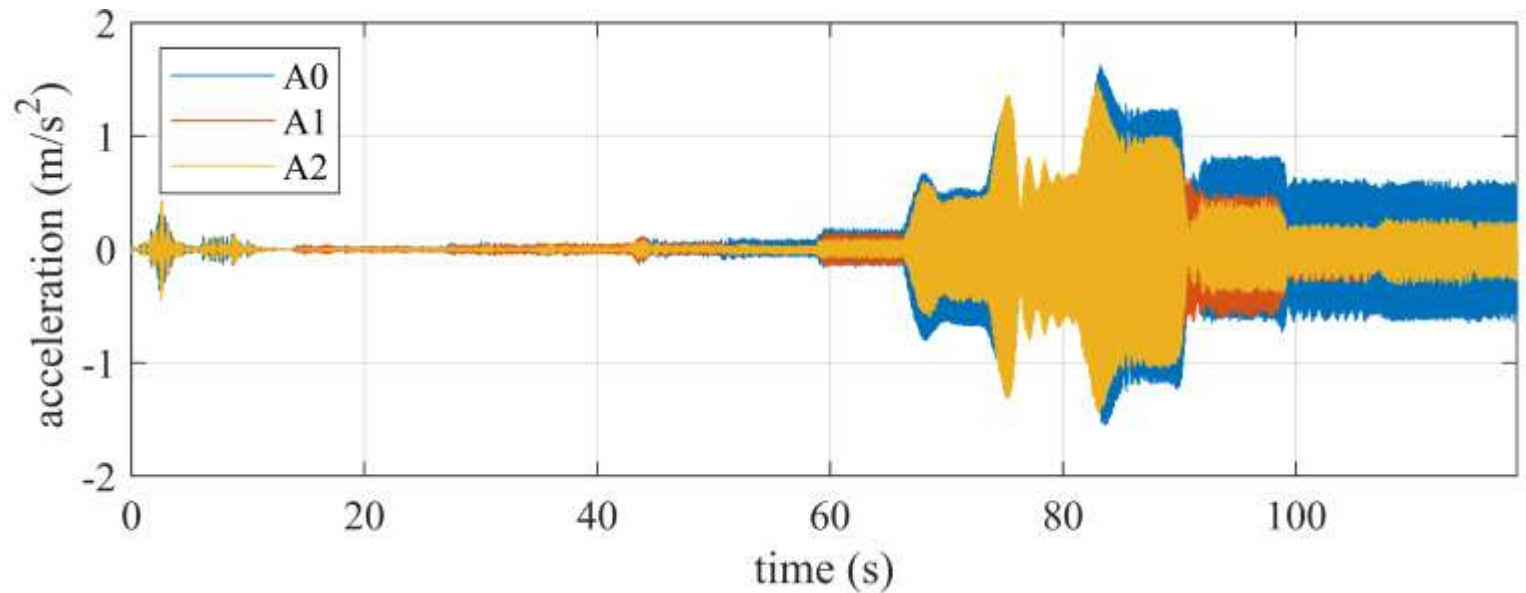
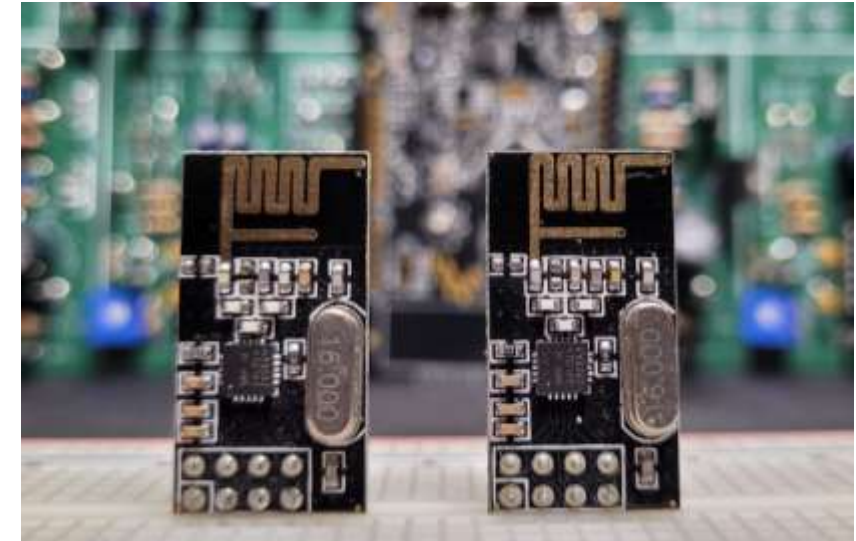
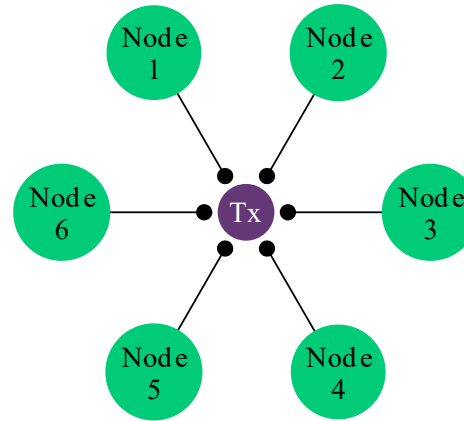
- MEMS accelerometer-based sensor
- Electropermanent magnet docking
- UAV-deployable capabilities
- Standalone power system
- Multi-link wireless communication
- Independent nonvolatile memory
- Real-time reference for data logging





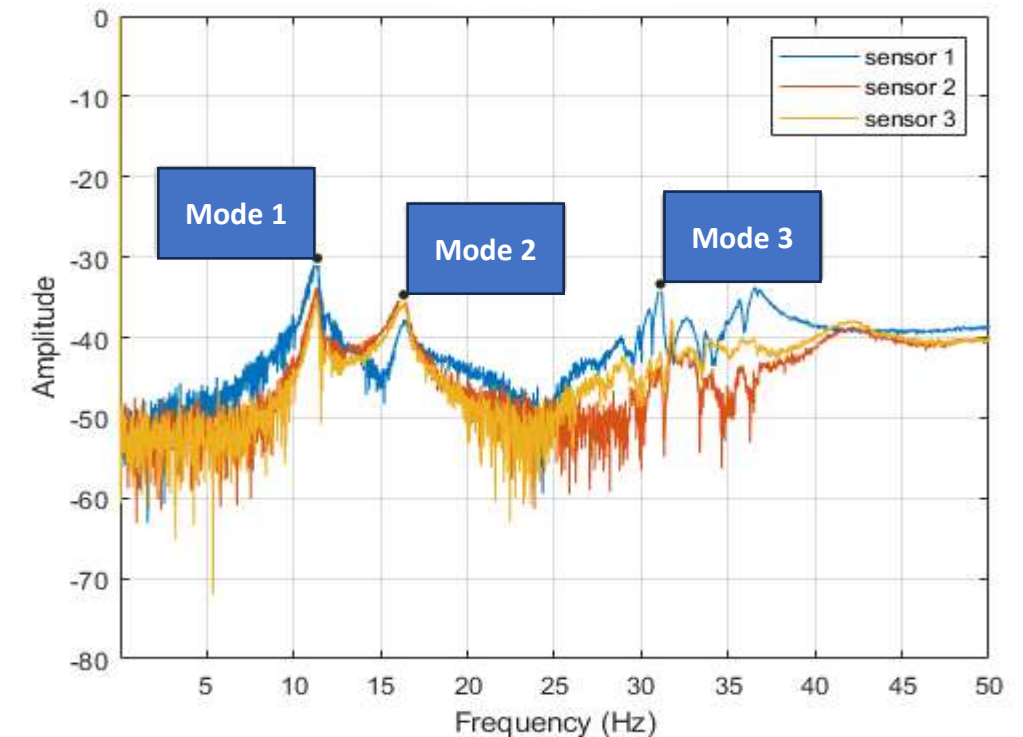
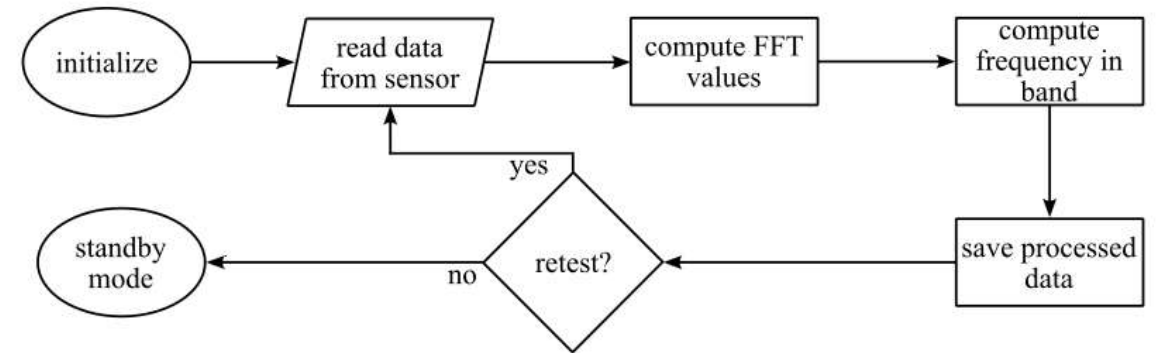
## Wireless sensing networks

- Wireless 2.4 GHz ISM Bandwidth
- Enhanced ShockBurst protocol
- Wireless range of 100 meters
- Transmission rate of 2Mbps
- Up to six radio links per hub
- Optimal for low-power sensing networks



## SHM edge-processing algorithm

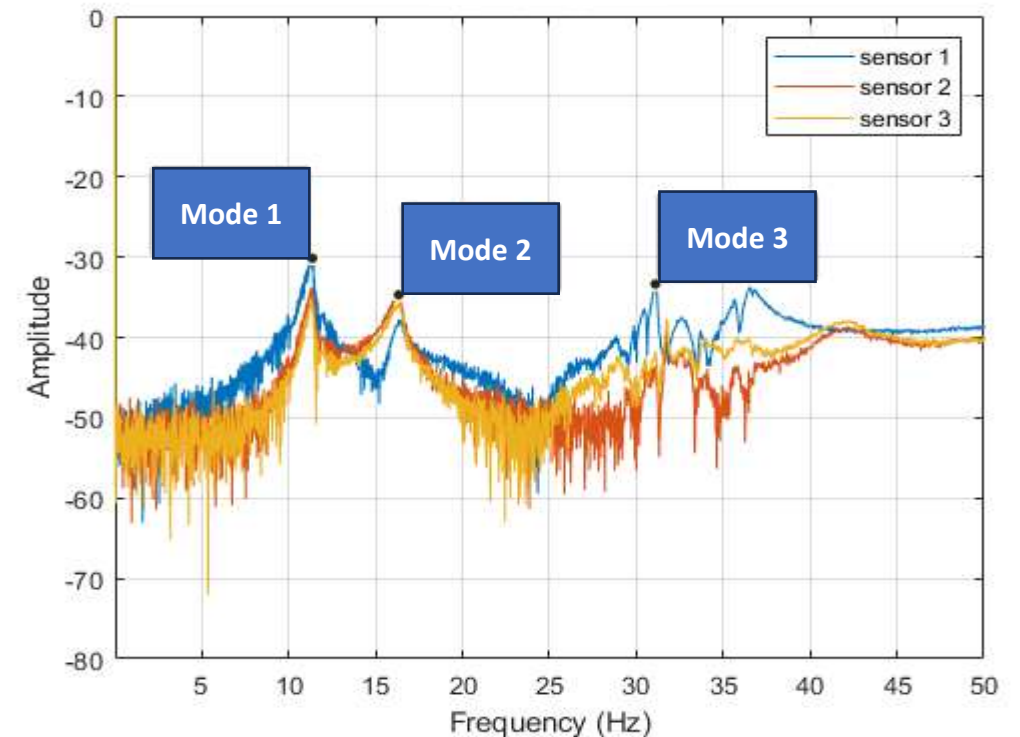
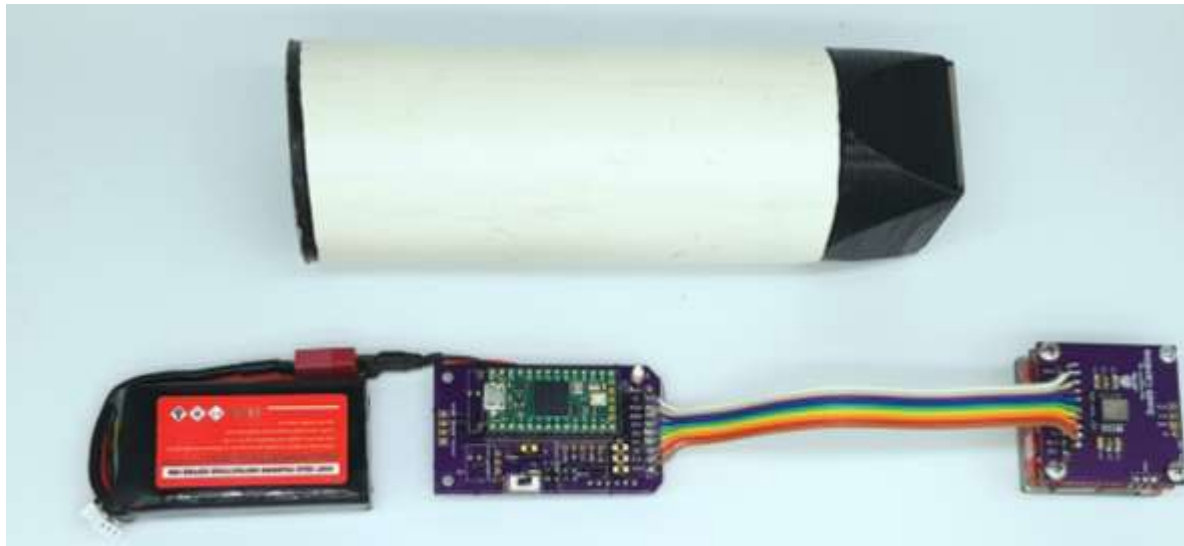
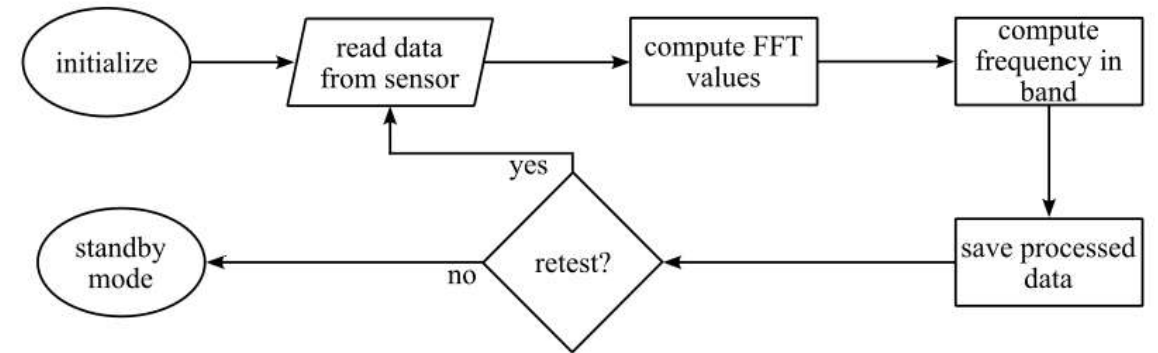
- Power and transmission bandwidth restrictions
- Conduct computation on the edge
  - Import time domain data directly from accelerometer
  - Compute the frequency-domain representation
  - Conditions the spectrum and detects frequency peaks
  - Extends deployment time by saving transmission power
  - Speeds up data processing and allows rapid assessment





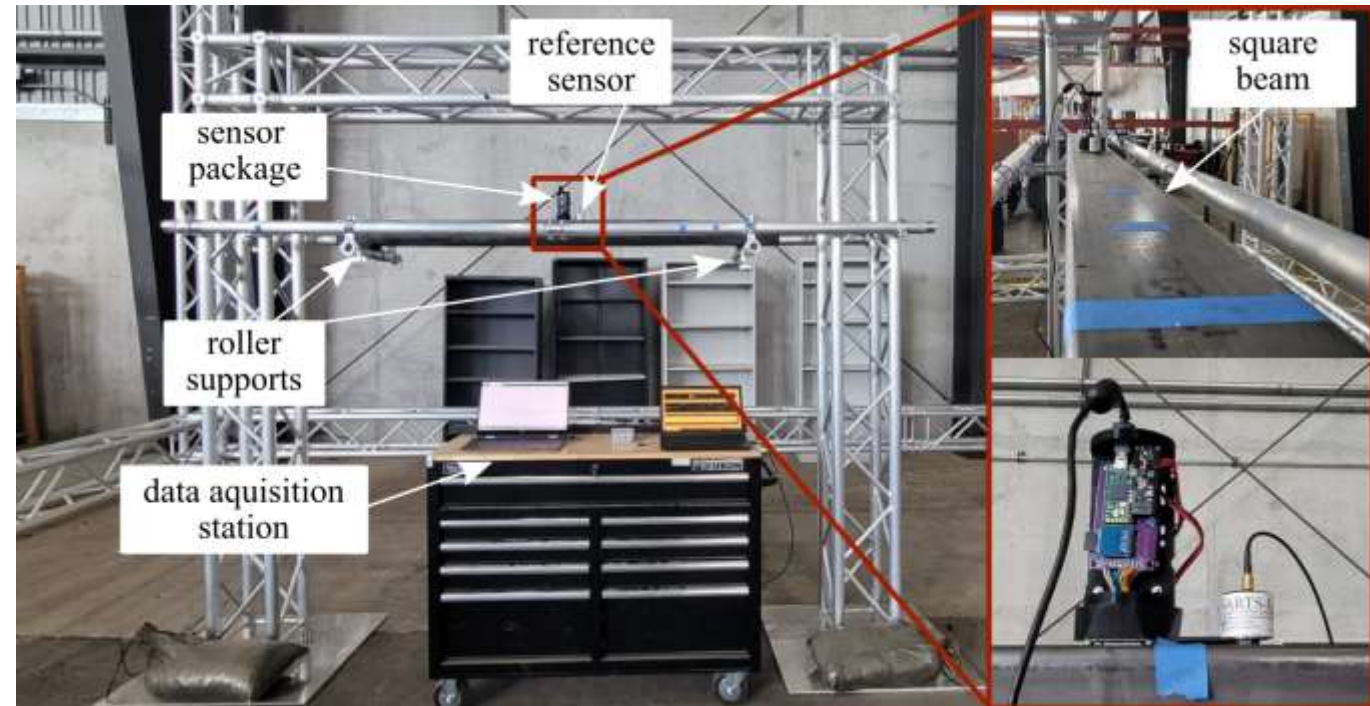
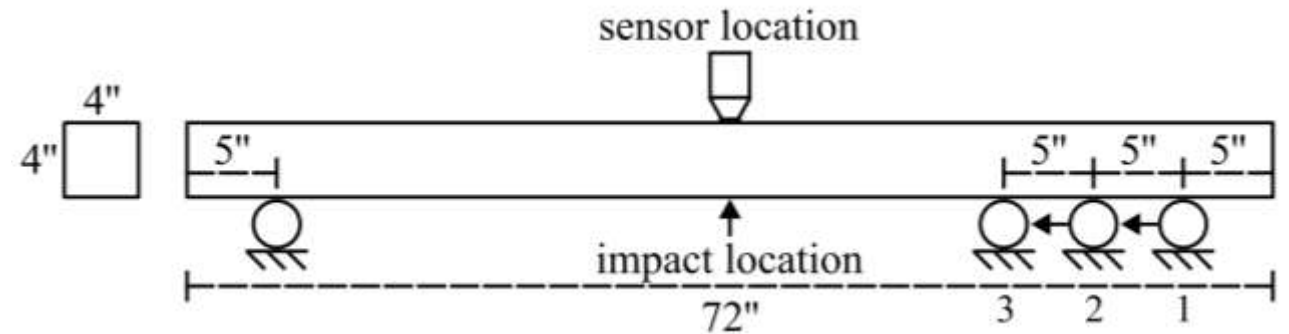
## SHM edge-processing algorithm

- Algorithm specifications:
  - Sampling rate of 1600 S/s
  - Buffer size of 16,000 Samples
  - FFT width: 8192 bins
  - FFT resolution: 0.098 Hz



## Modal frequency detection using UAV-deployable edge-computing sensing node

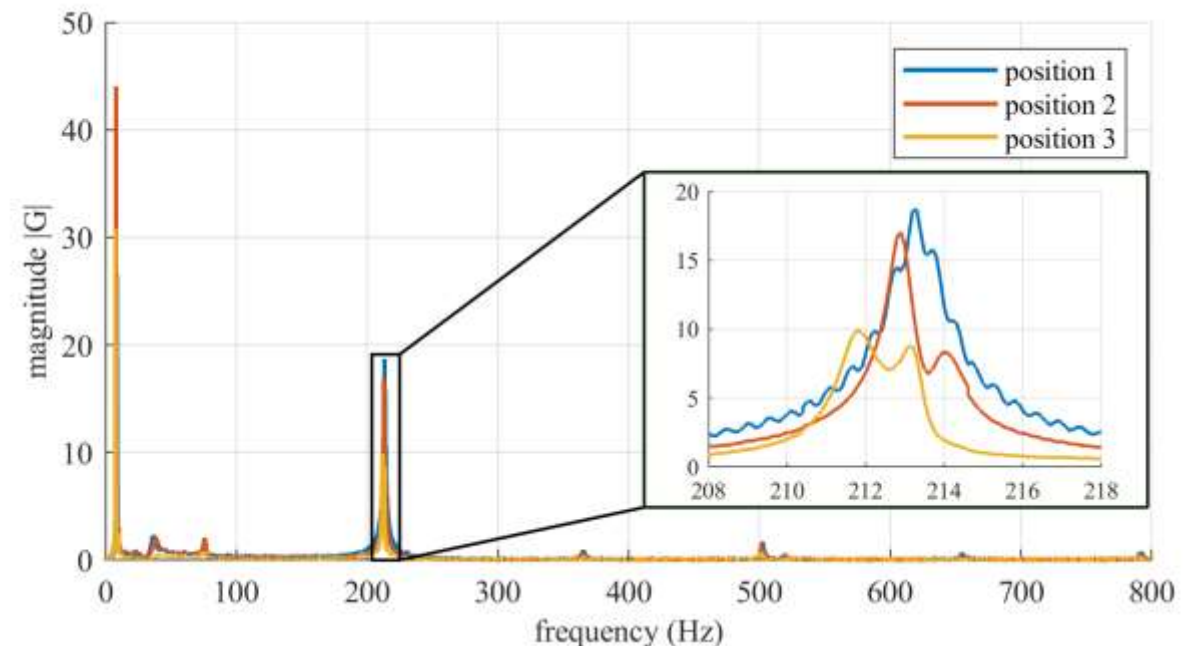
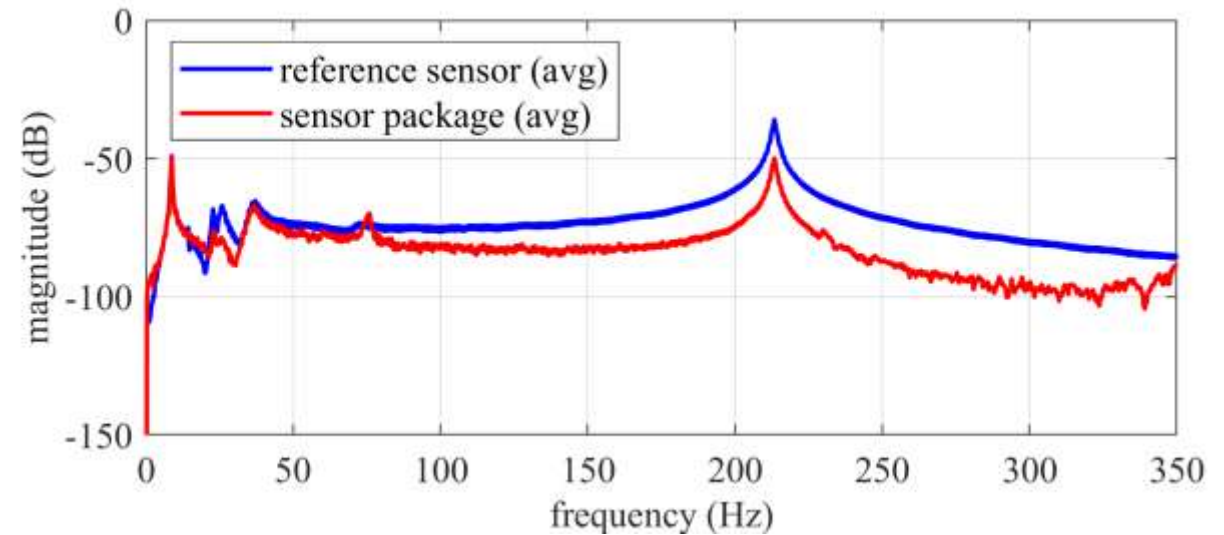
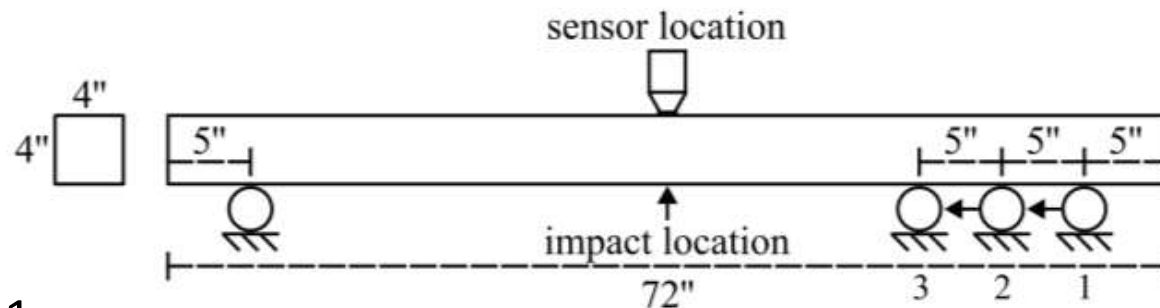
- Experiment consists of a structure suspended over to rollers.
- One roller is shifted to three different states
- The three states alter the frequency response
- The goal is to validate the algorithm's ability to detect a change in modal frequencies on edge
- A superior reference accelerometer is used for ground truth measurement



## Frequency response analysis

- Experiment consists of a structure suspended over to rollers.
- One roller is shifted to three different states
- The three states alter the frequency response
- The goal is to validate the algorithm's ability to detect a change in modal frequencies on edge
- A superior reference accelerometer is used for ground truth measurement

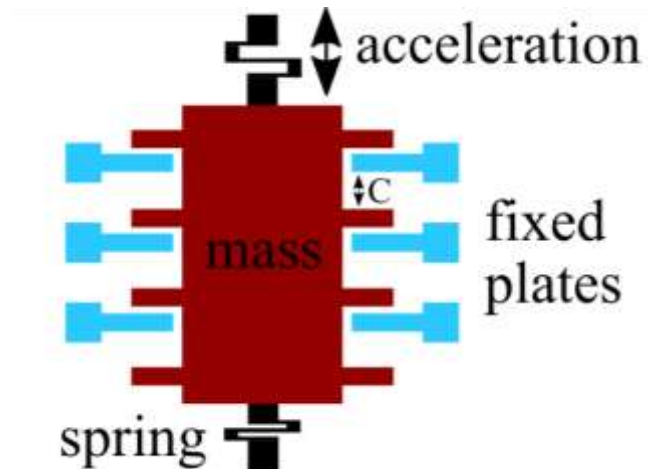
Position	Frequency (Hz)	Magnitude (G)
1	213.02	18.68
2	212.63	17.05
3	212.11	9.91





## Sensing system strengths and experimental challenges

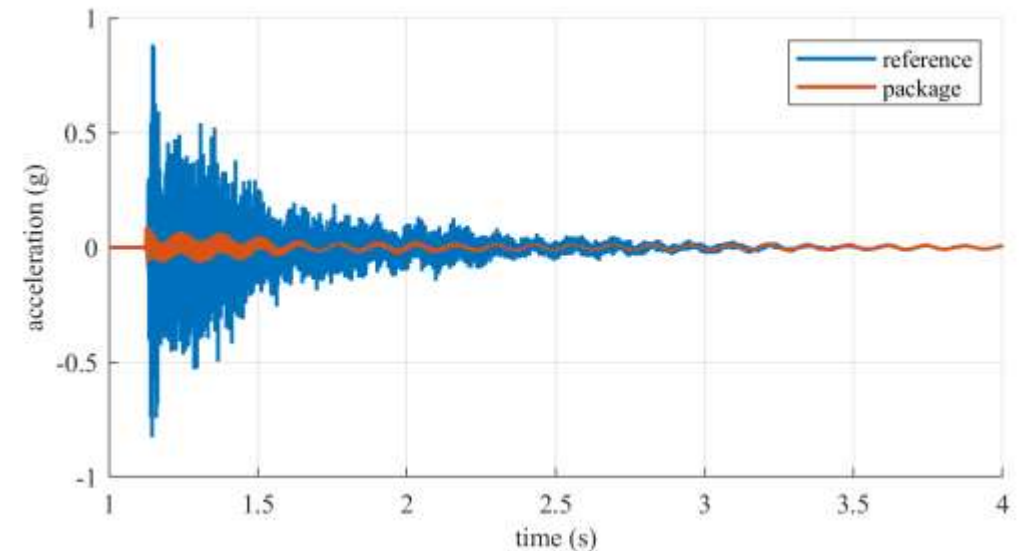
- Sensor package fails to capture time domain vibration magnitude accurately
- Suspected error due to mechanical transmissibility loss through the electro permanent magnet assembly
- A signal conditioning and error compensation algorithm is currently under development to combat this challenge



reference

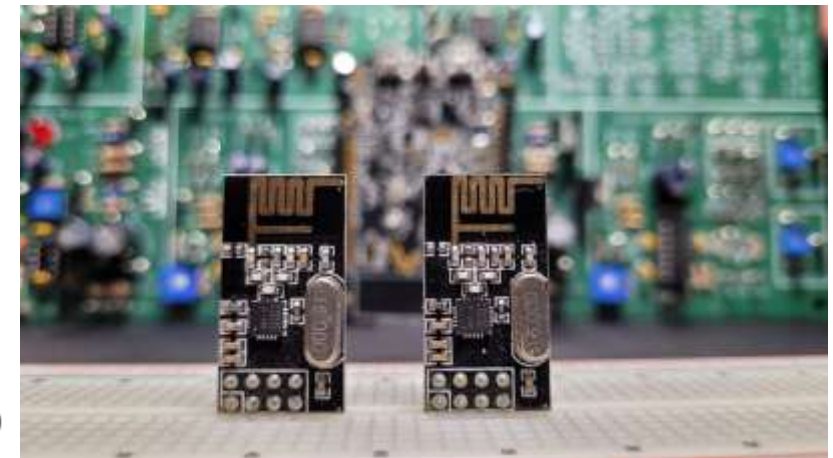
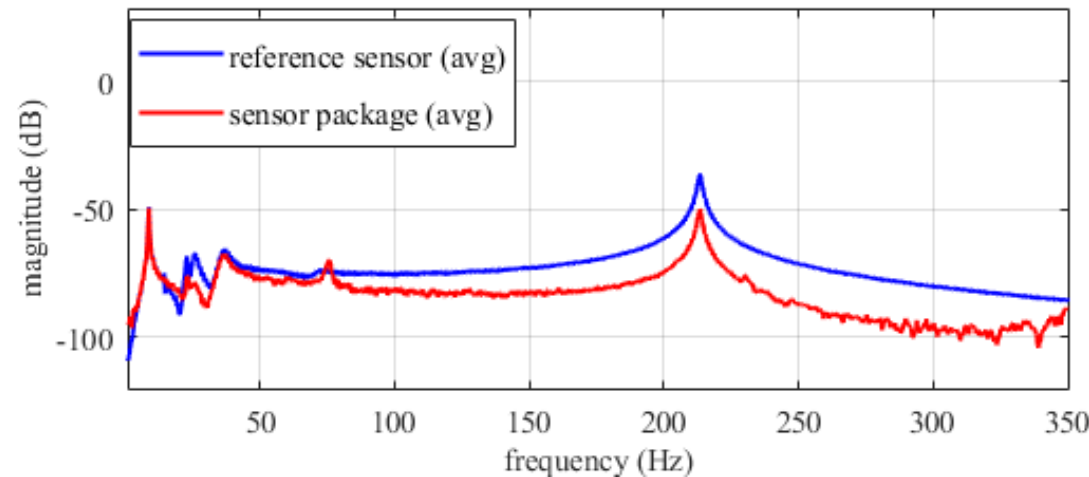
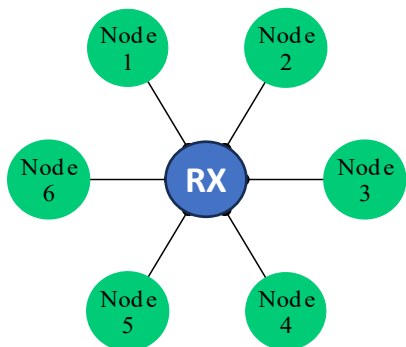


sensor package



## Sensing system improvements

- Sensor network algorithm enhancements to allow for rapid modal reconstruction on-edge using multiple sensing nodes



## ACKNOWLEDGMENT

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Open-Source hardware Designs



<https://github.com/ARTS-Laboratory/Drone-Delivered-Vibration-Sensor>



Open-source UAV-deployable vibration sensor package

Thanks for listening

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