

# Case Study for using Open-Source UAV-deployable Wireless Sensor Nodes for Modal-based Monitoring of Civil Infrastructure

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Methodology

Experimentation

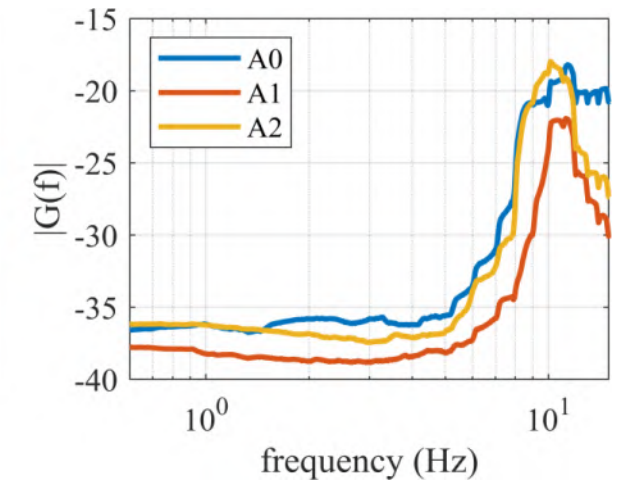
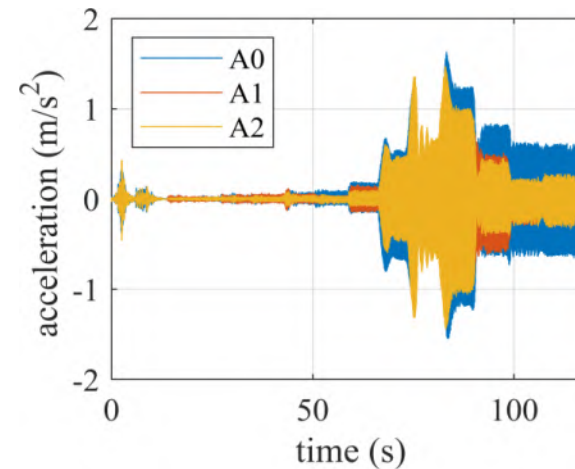
Results and Discussion

Future work



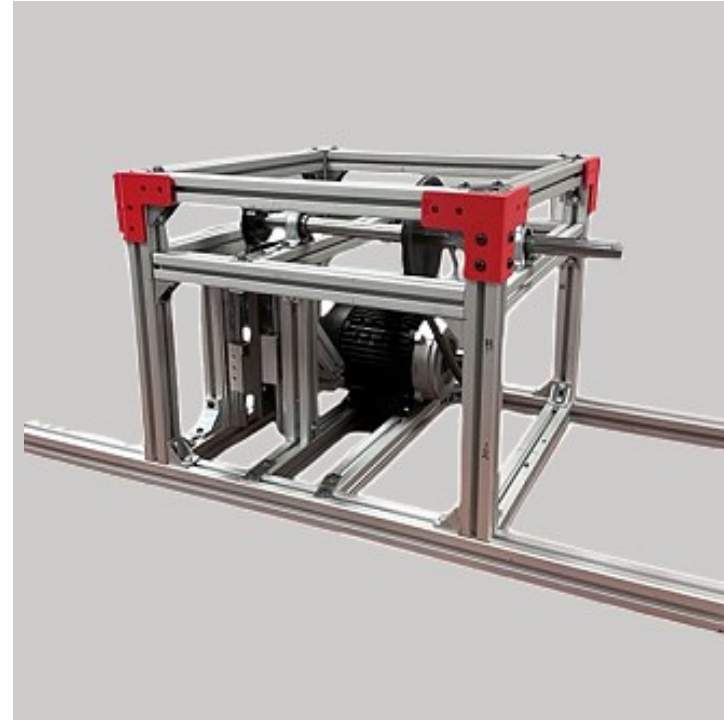
## Outline

- Introduction:
  - rapid structural health monitoring
  - modal analysis for structural state estimation
  - rapid SHM sensing systems
- Methodology:
  - UAV-deployable sensor hardware
  - sensing network algorithm breakdown
  - active SHM using external excitation
- Experimentation:
  - case study of active modal detection using UAV-deployable sensing network on a pedestrian bridge
- Results and Discussion:
  - time and frequency responses
  - sensing system strengths and experimental challenges
- Future work:
  - sensor network algorithm enhancements
  - rapid modal reconstruction on-edge



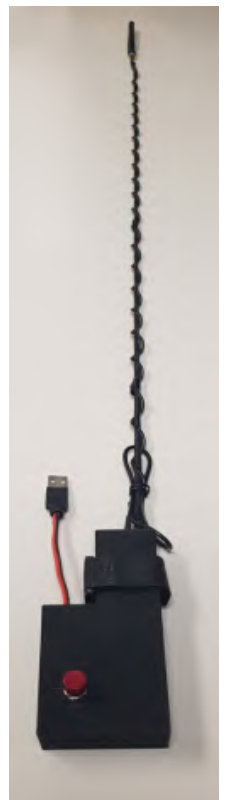
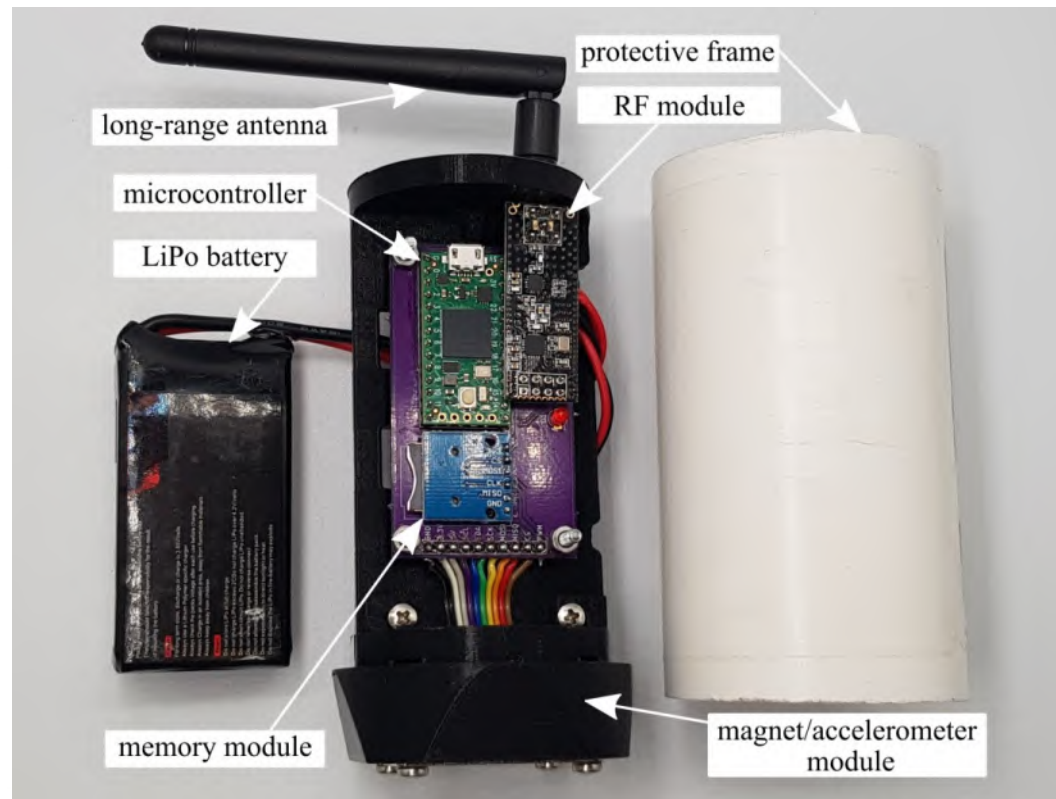
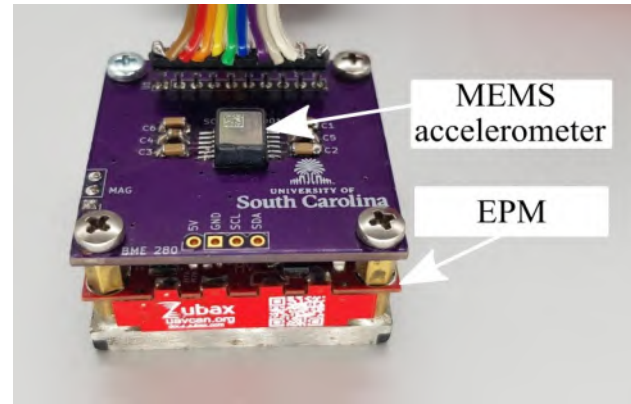
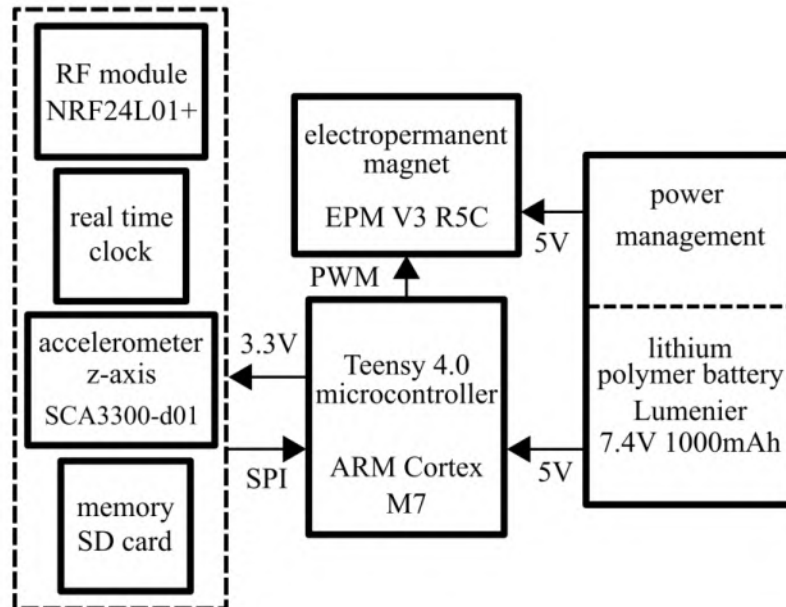
## Introduction

- rapid structural health monitoring
- modal analysis for structural state estimation
- rapid SHM sensing systems



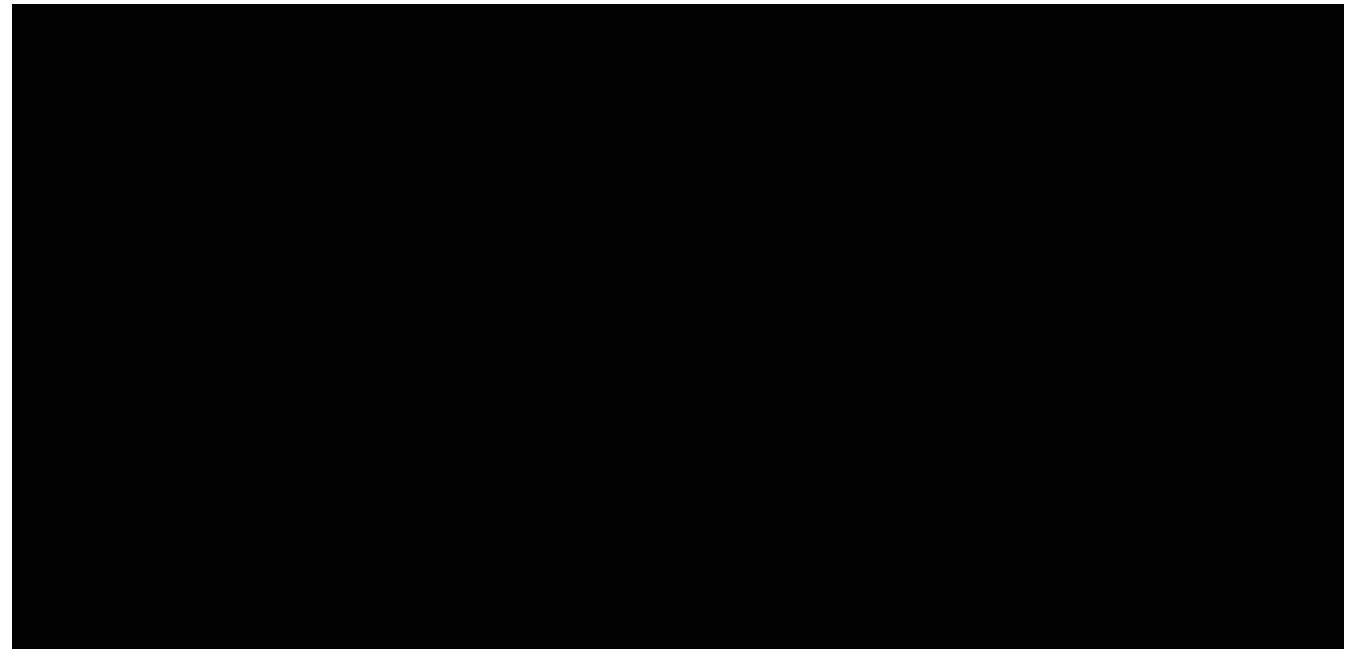
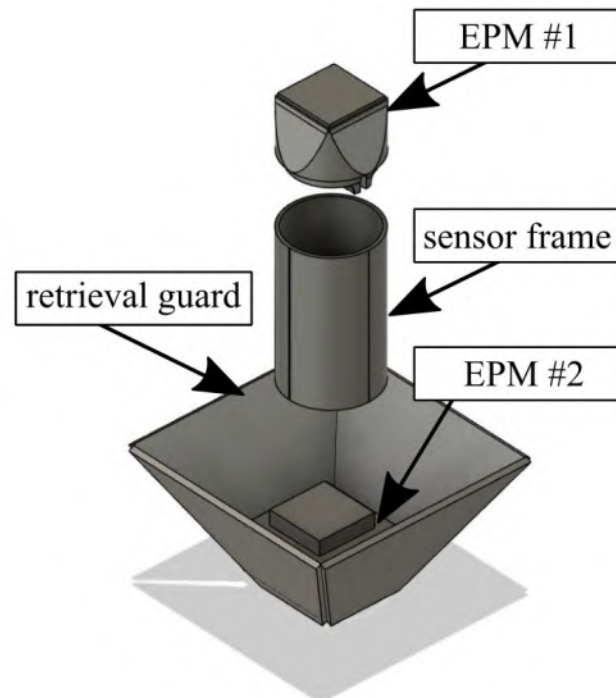
## UAV-deployable sensor hardware

- features:
  - MEMS accelerometer-based sensor
  - standalone power system
  - multi-link wireless communication
  - independent nonvolatile memory
  - real-time reference for data logging
  - electropermanent magnet-based docking
  - UAV-deployable capabilities



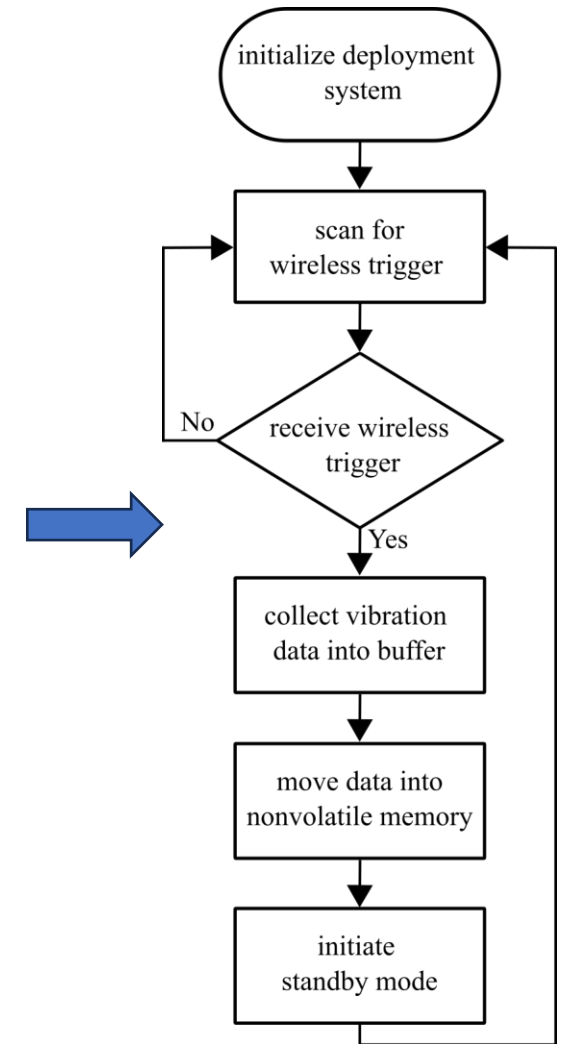
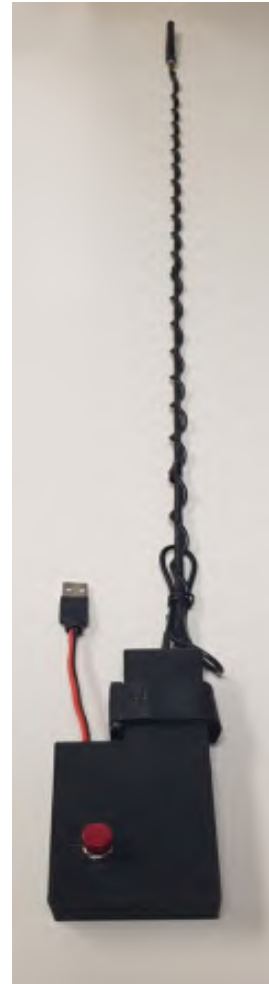
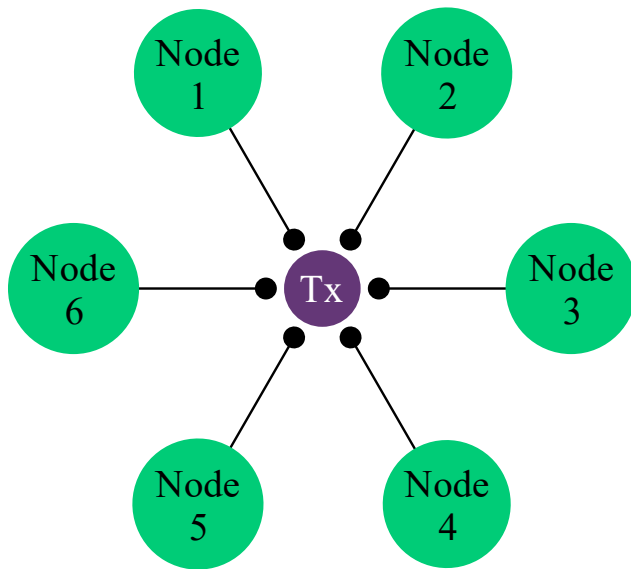
## UAV-deployable sensor hardware

- Deployment and retrieval system
  - Hexcopter drone
  - Two electro permanent magnets
  - Retrieval guard
  - Standalone control system



## sensing network algorithm breakdown

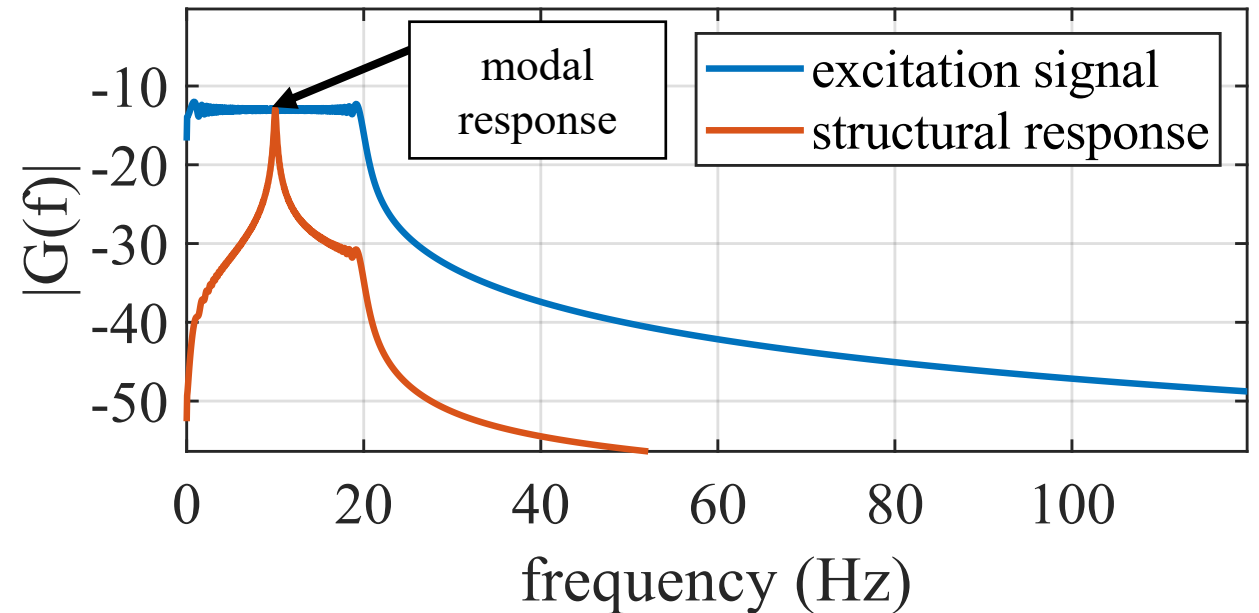
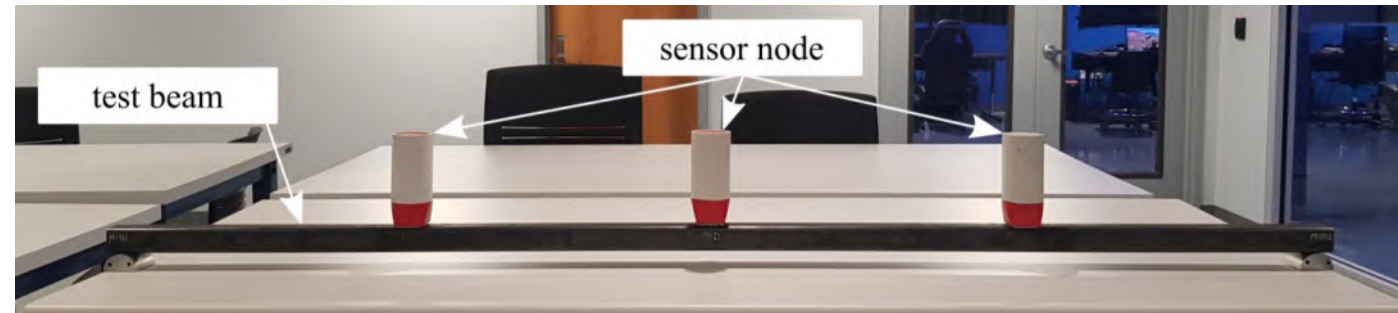
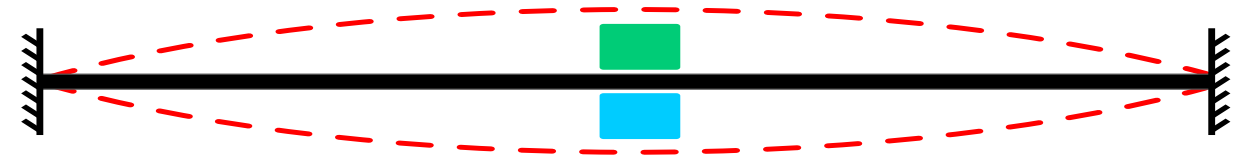
- protocol: Enhanced ShockBust
- bandwidth: 2.4 GHz
- data rate: 2 Mbps
- RF links: 6 channels



## active SHM using external excitation

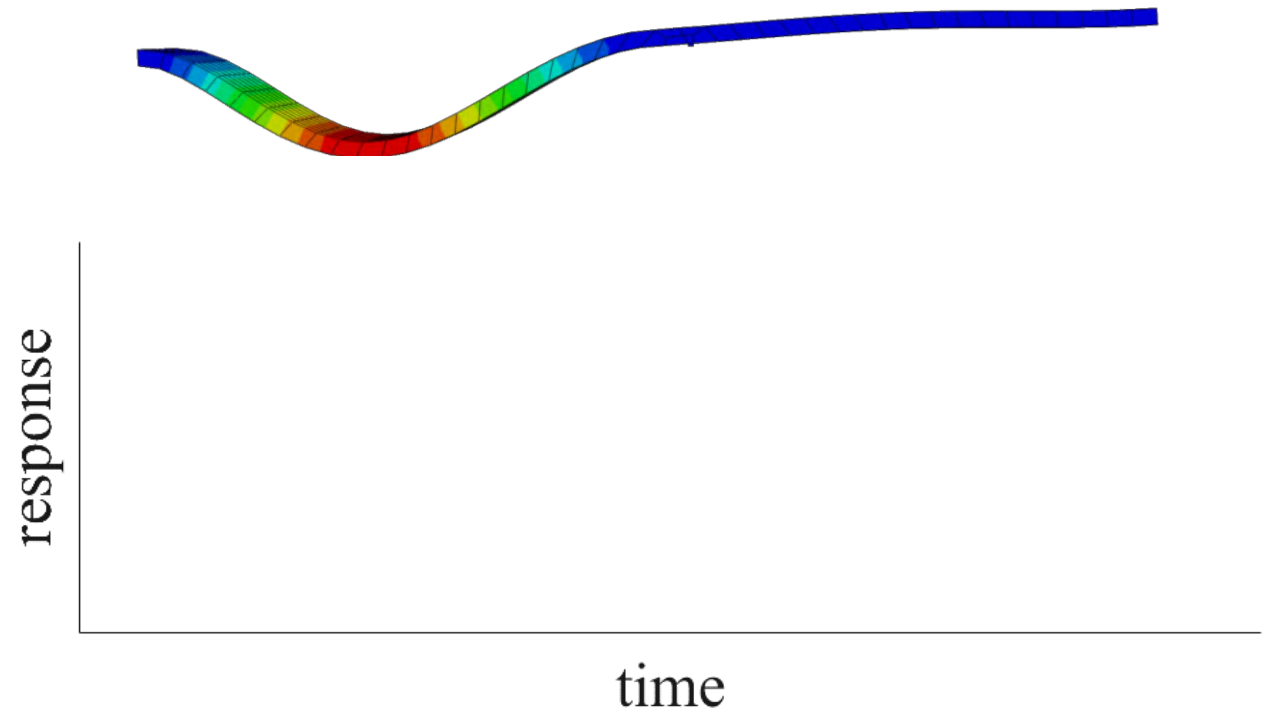
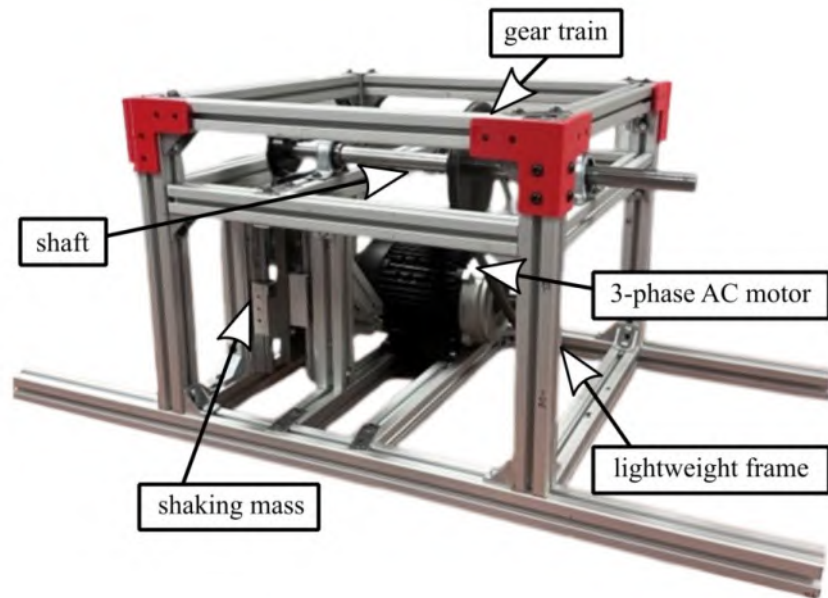
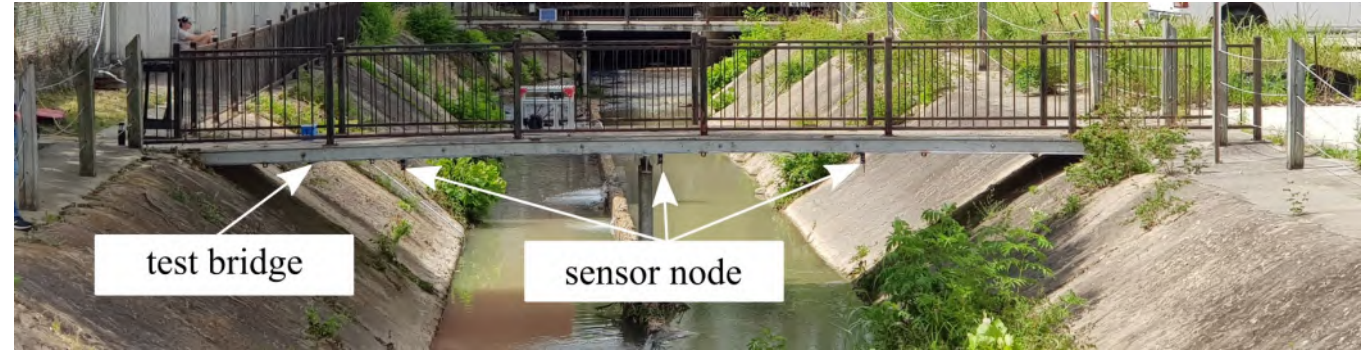
- sensors and actuators
- data acquisition and signal processing
- dynamic response and modal detection

- structural shaker
- sensor package



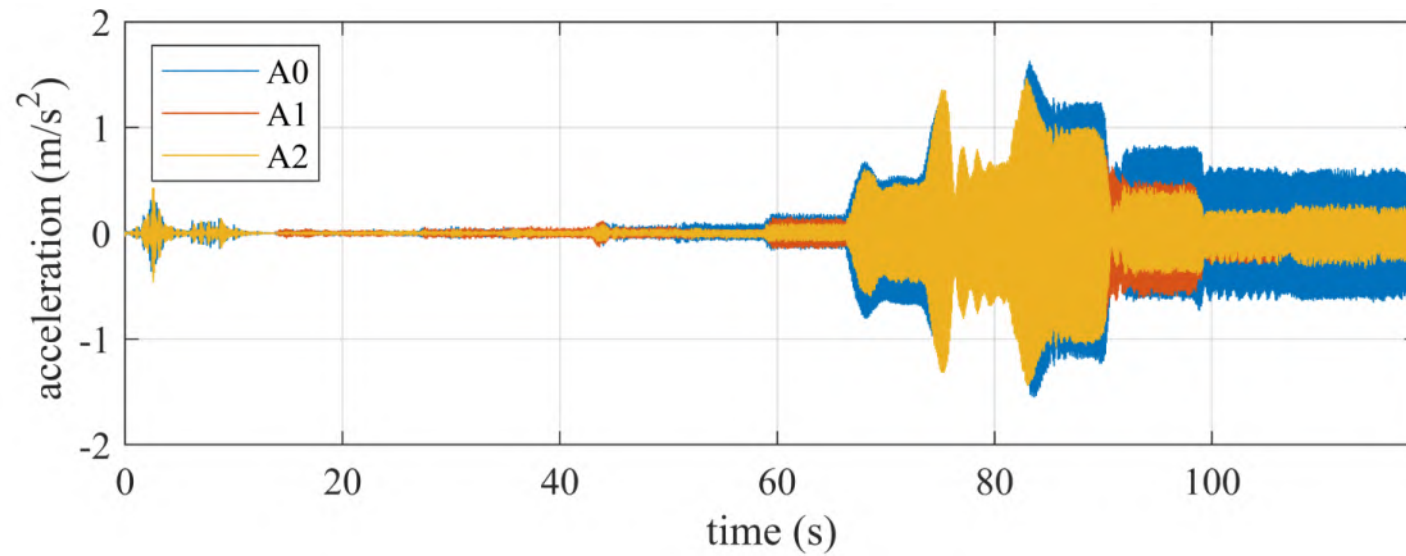
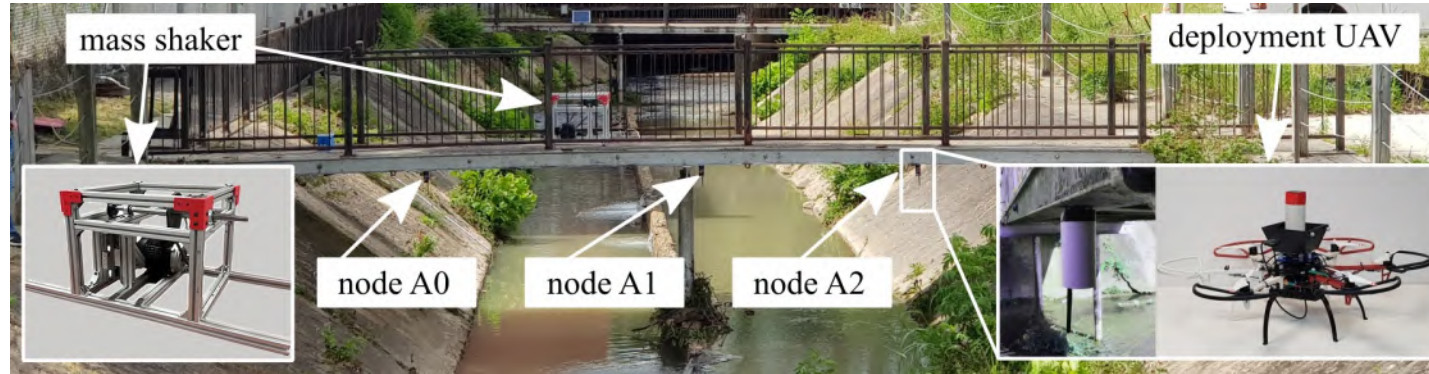
## active modal detection using UAV-deployable sensing network

- data acquisition and real-time synchronization
- signal processing and state estimation

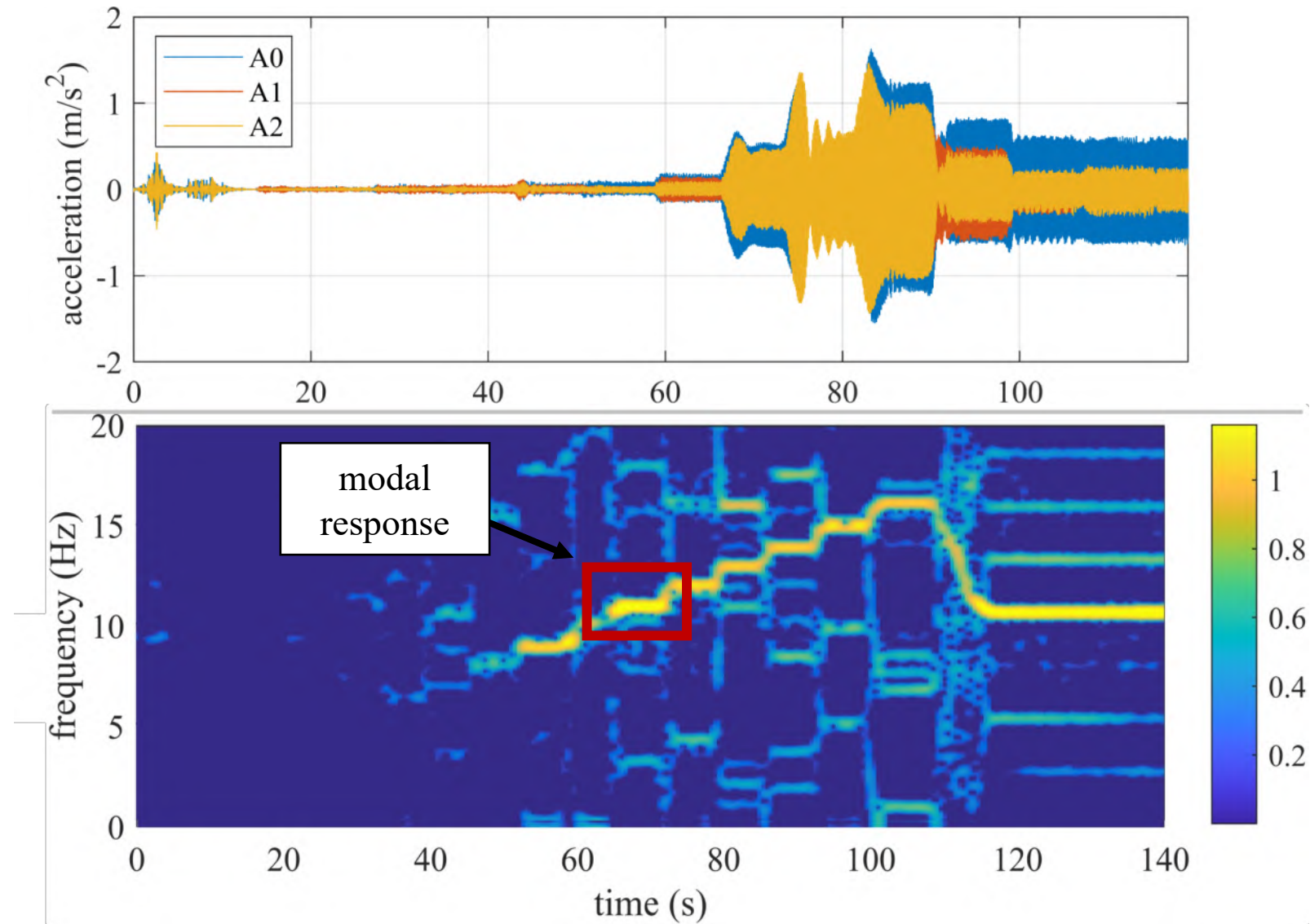




## time and frequency response

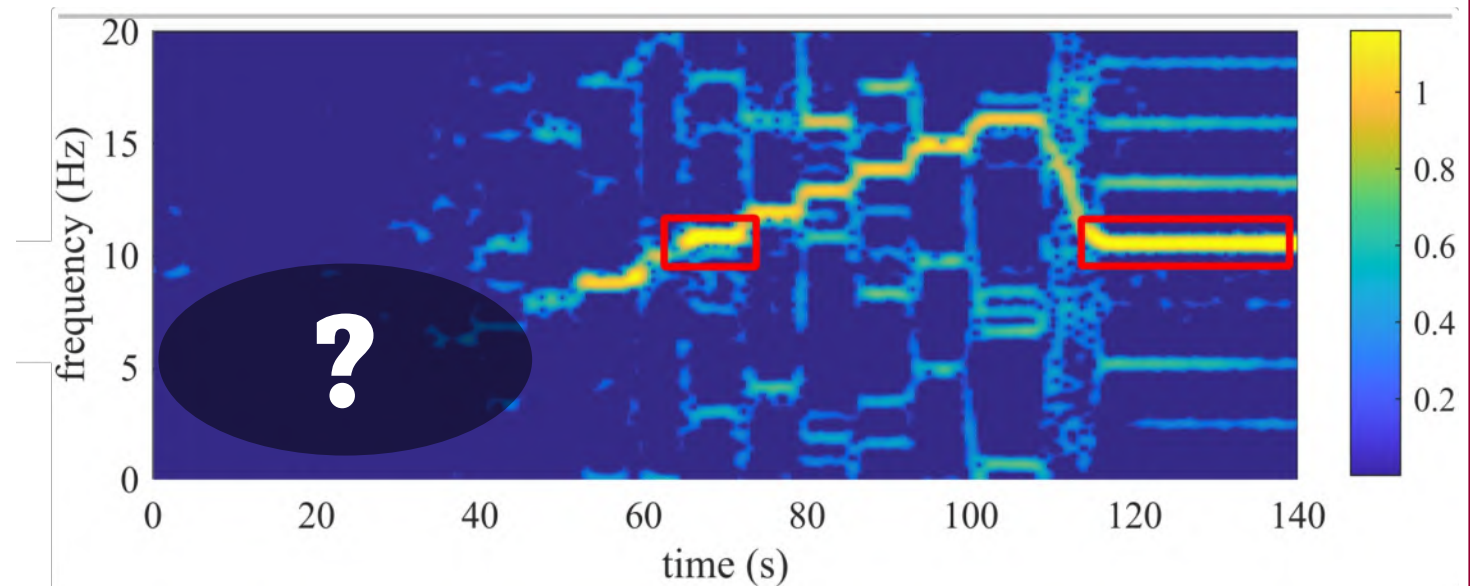
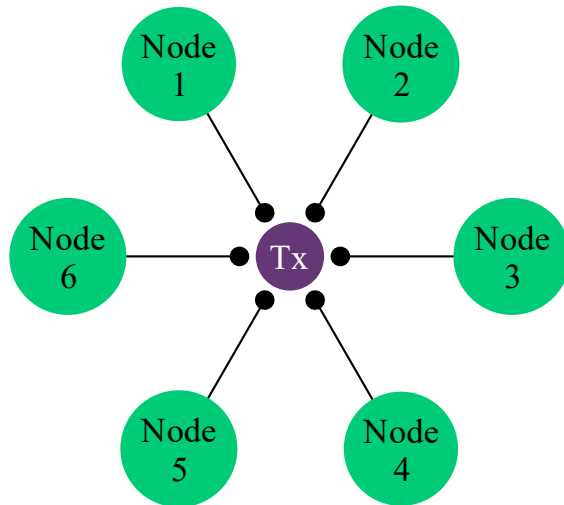
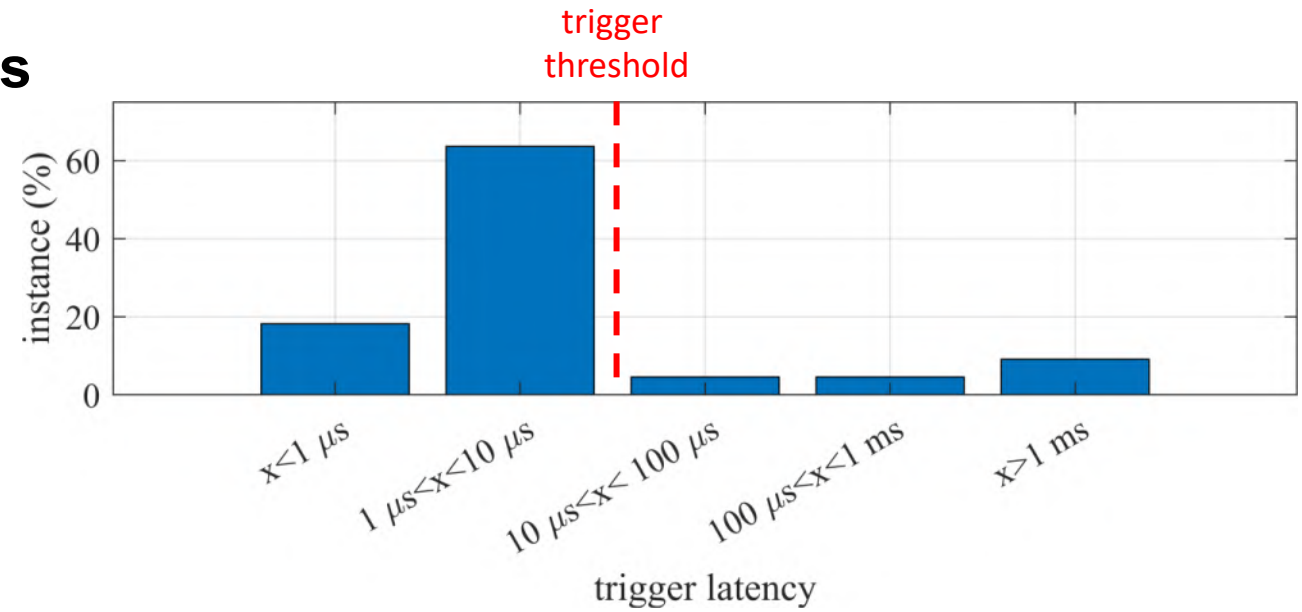


## time and frequency response

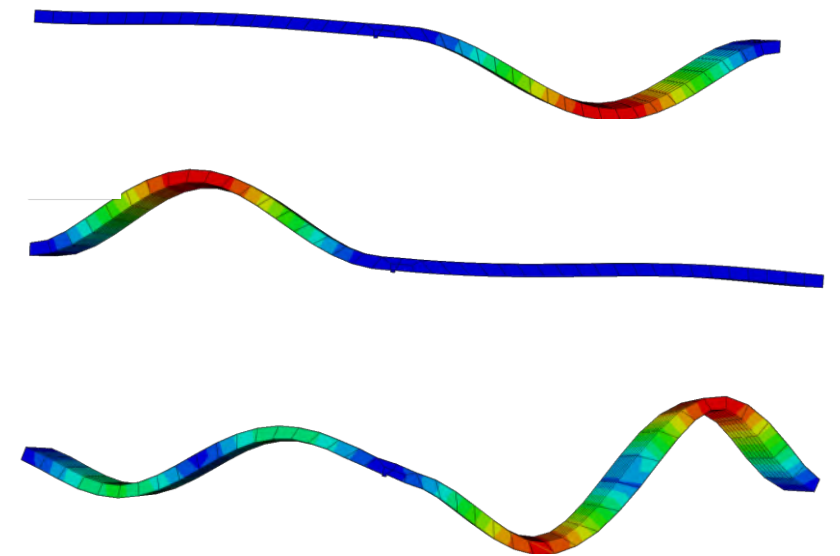
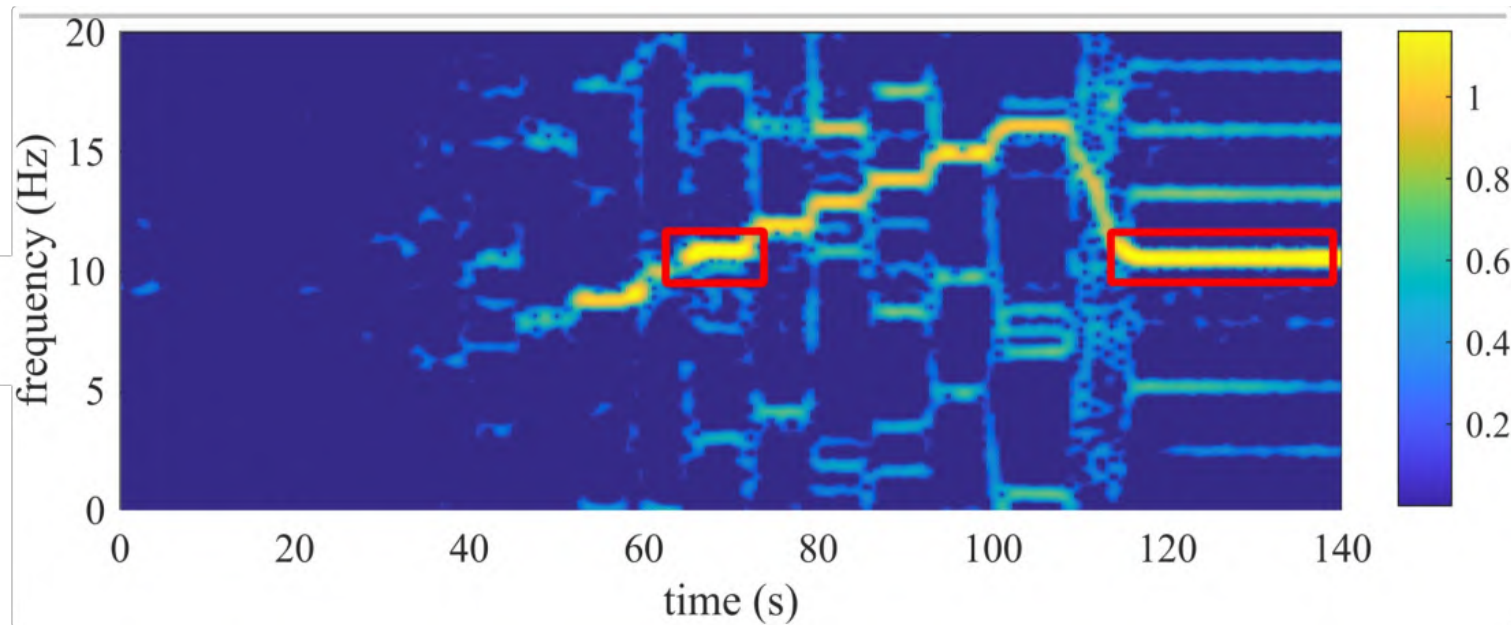


## sensing system experimental challenges

- wireless trigger time latency ( $\sim 85\% < 10 \mu\text{s}$ )
- low-magnitude low-frequency response detection



- Sensor network algorithm enhancements for error-handling and data transfer
- Modal reconstruction on-edge for rapid state assessment and prognostics



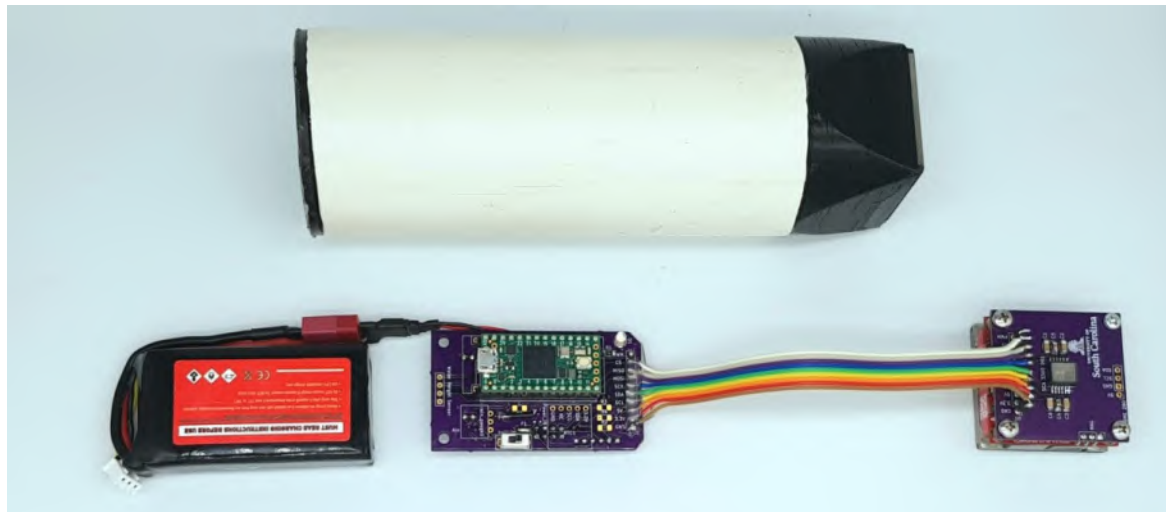
## Open-source UAV-deployable vibration sensor package



Open-Source hardware Designs



<https://github.com/ARTS-Laboratory/Drone-Delivered-Vibration-Sensor>



## ACKNOWLEDGMENT

This material is based upon work supported by the National Science Foundation grant numbers 2152896 and 2237696 with additional support from the Air Force Office of Scientific Research (AFOSR) through award no. FA9550-21-1-0083. Any opinions, findings, and conclusions or recommendations expressed in this material are those of the authors and do not necessarily reflect the views of the National Science Foundation, or the United States Air Force.



**Thank you**

**Questions?**

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